







Physics-Dynamics Coupling with Galerkin methods: Equal-Area Physics Grid

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Workshop on Physics-dynamics coupling in geophysical models – bridging the gap December 2-4, 2014 CICESE, Ensenada, Mexico

Getting away from the lat-lon grid ...

CAM=NCAR's Community Atmosphere Model





- Scalability
- Static meshrefinement capability
- ...

CAM-FV (finite volume)

Lin (2004)

CAM-SE (spectral elements)

Dennis et al., (2012)





CAM-SE (spectral element dynamical core); (Dennis et al., 2012)

CAM-SE uses a continuous Galerkin finite element method (Taylor et al., 1997) referred to as **Spectral Elements (SE)**:

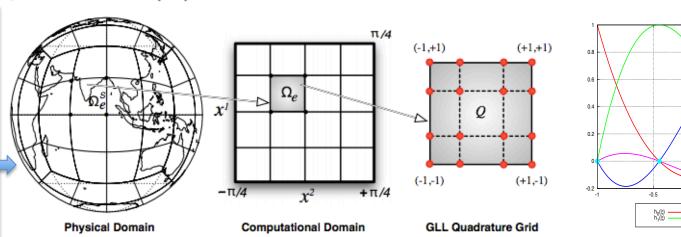






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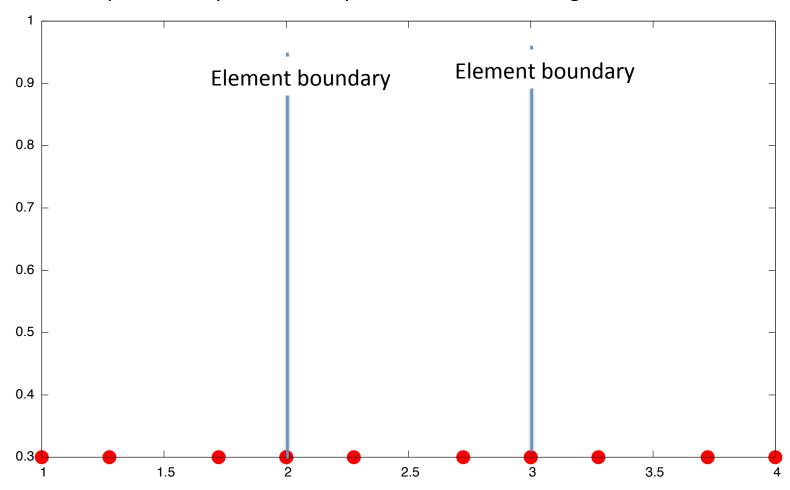
- Physical domain: Tile the sphere with quadrilaterals using the gnomonic cubed-sphere projection
- Computational domain: Mapped local Cartesian domain
- Each element operates with a Gauss-Lobatto-Legendre (GLL) quadrature grid

 Gaussian quadrature using the GLL grid will integrate a polynomial of degree 2N 1 exactly, where N is degree of polynomial
- Elementwise the solution is projected onto a tensor product of 1D Legendre basis functions
 by multiplying the equations of motion by test functions; weak Galerkin formation
 - → all derivatives inside each element can be computed analytically!





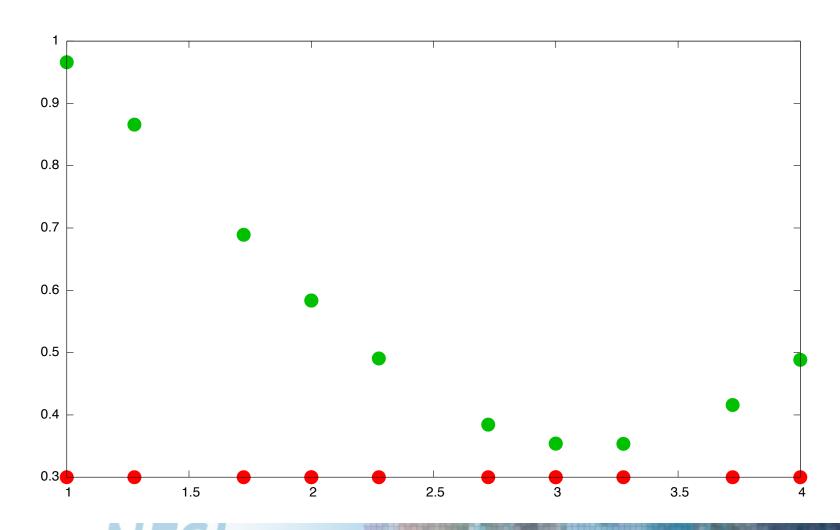
- Computational grid: 3 elements, 4 quadrature points in each element (np=4)
- This quadrature will integrate polynomials of degree 3 exactly
- Note: quadrature points are duplicated on element edges







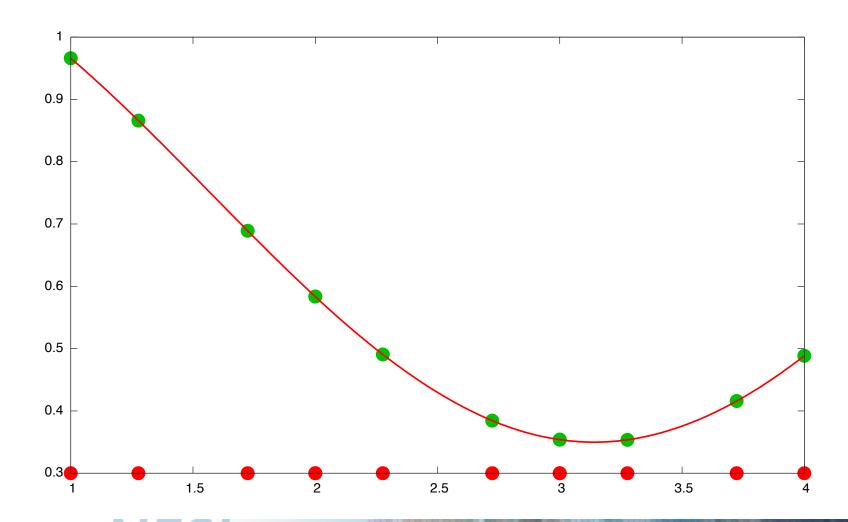
Let the initial condition for GLL point values be a degree 3 polynomial







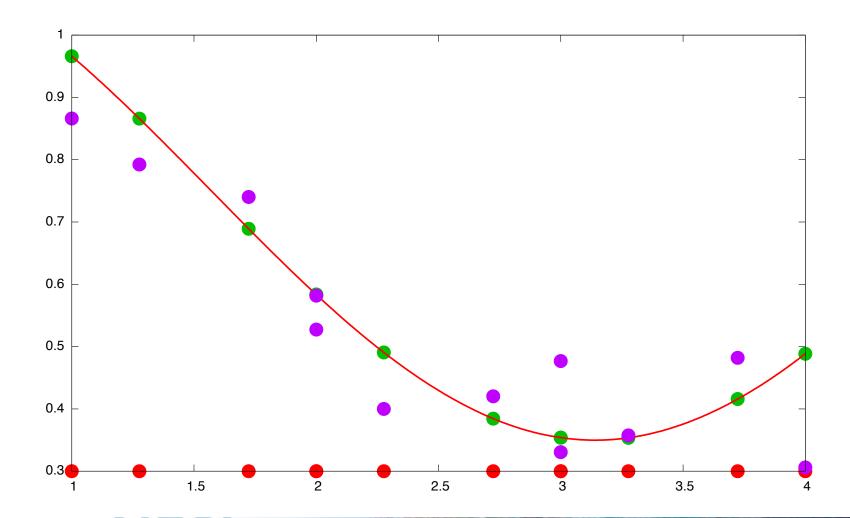
- Let the initial condition for GLL point values be a degree 3 polynomial
- The polynomial basis exactly represents initial condition







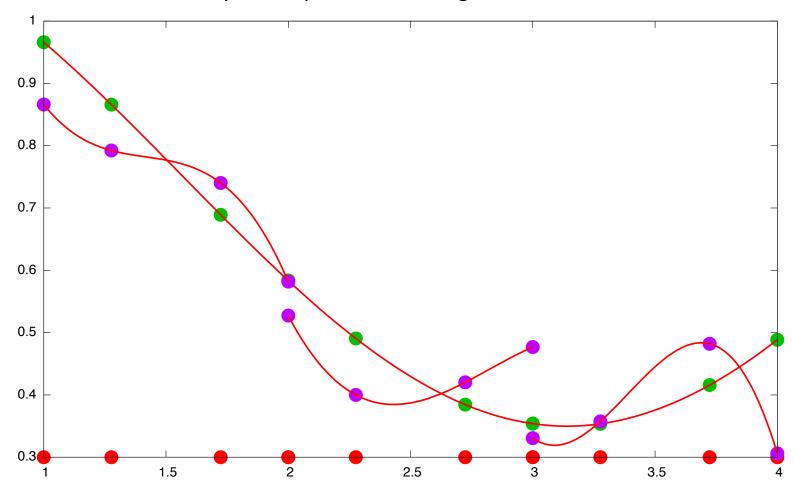
- Within each element the dynamical core advances one Runga-Kutta step
- Note each element advances the solution in time independently







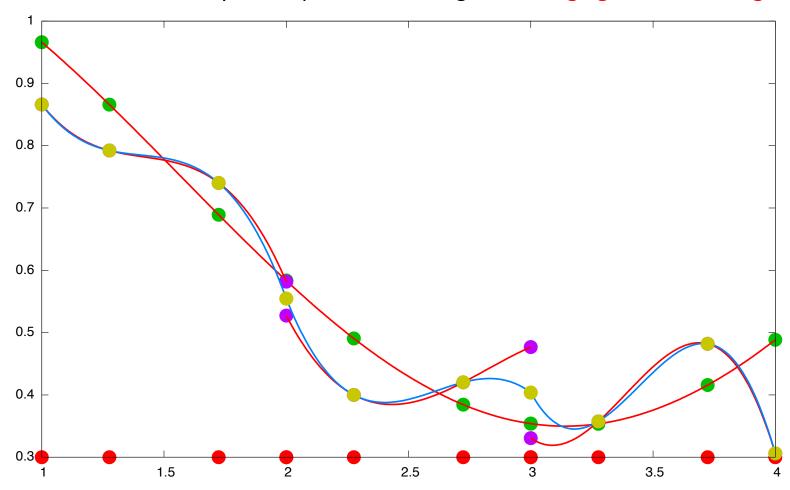
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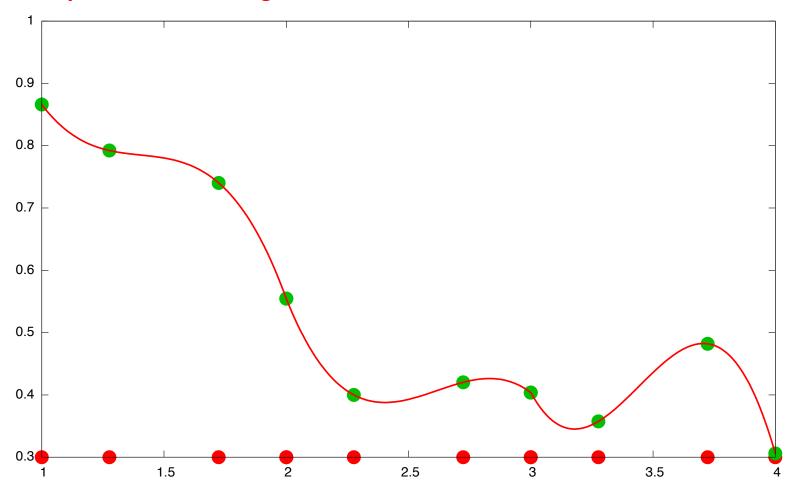
- Within each element the dynamical core advances one Runga-Kutta step
- Note each element advances the solution in time independently
- Discontinuities may develop at element edges averaging at element edges







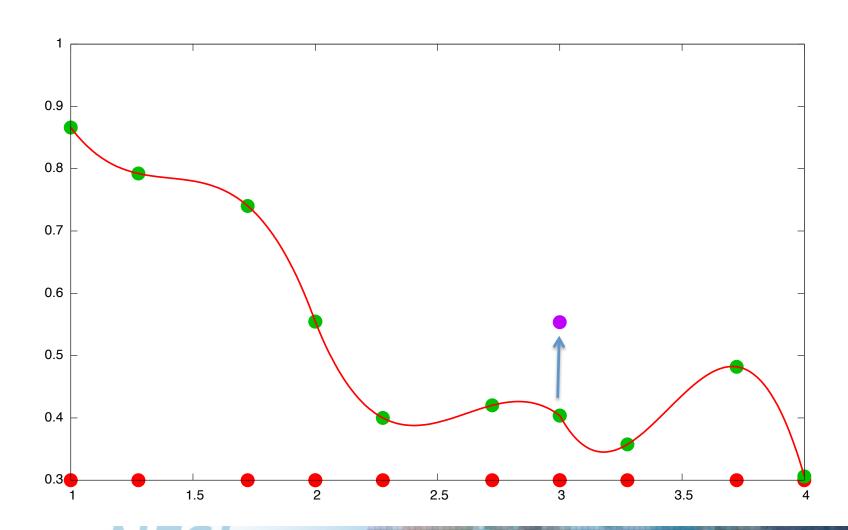
- This process is repeated for every Runga-Kutta stage (currently 5 times per dynamics time-step)
- Physics is "run on GLL grid"







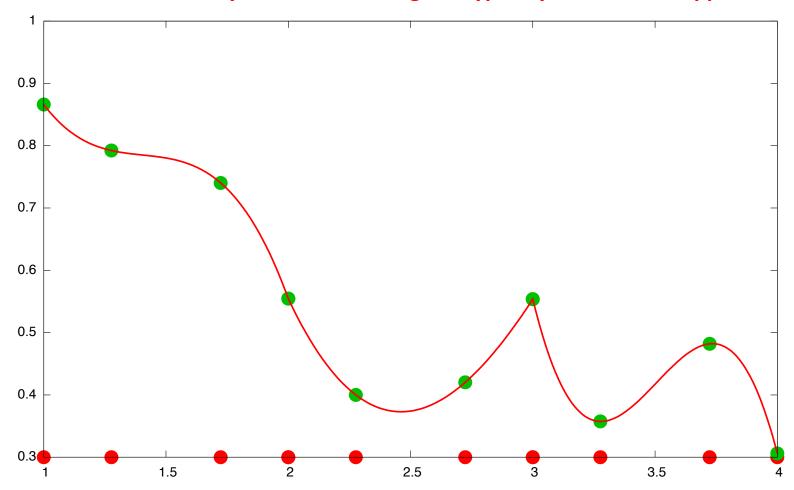
Physics update: say it perturbs one point value







- Physics update: say it perturbs one point value
- Polynomial basis changed in element 2
- Basis functions only C⁰ at element edges typically where noise appears



CAM-SE dynamical core properties

- Discretization preserves adjoint properties of divergence, gradient and curl (mimetic)
 - -> CAM5.2 conserves moist energy
 - -> Machine precision mass-conservation (at the element level)
- Option to run with Eulerian finite-difference discretization (CAM5.2) in the vertical and floating Lagrangian vertical coordinates (CAM5.3)
- Supports static mesh-refinement (and retains formal order of accuracy)
- Conserves axial angular momentum very well (Lauritzen et al., 2014)
- CAM-SE is hydrostatic

How do we couple the dynamical core with sub-grid scale parameterizations (physics)?

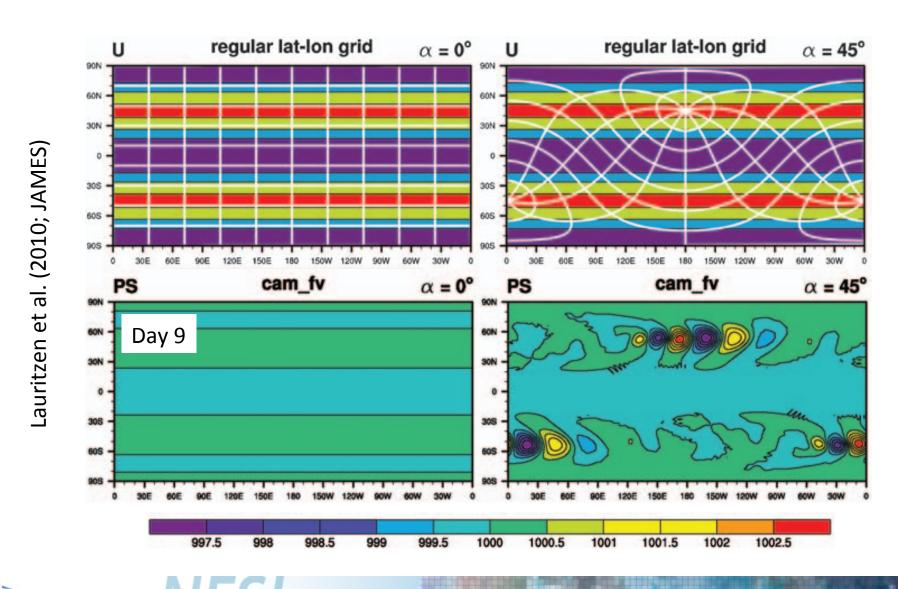


Traditionally physics and dynamics grids are collocated

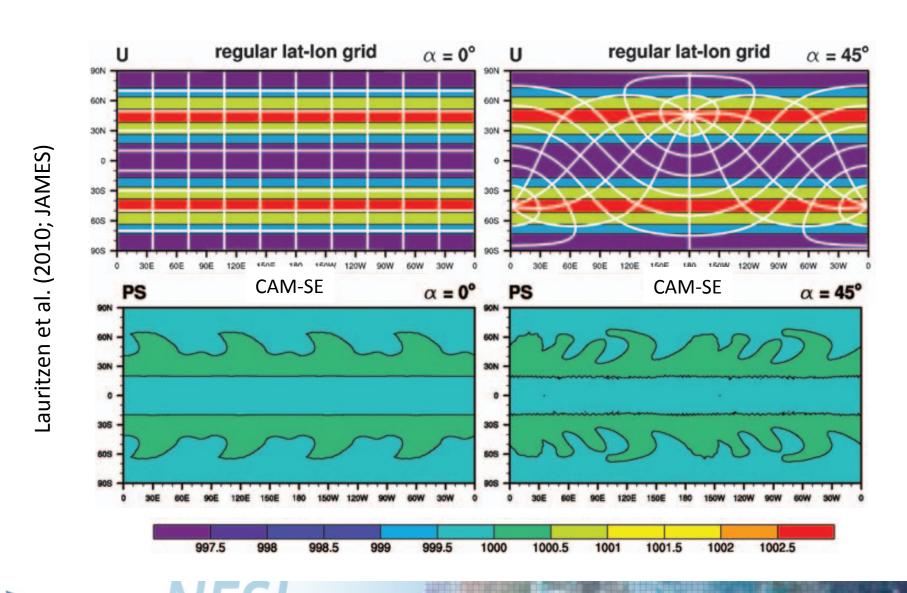


- smoothly varying grid in terms of grid size
- Much higher resolution near poles, however, dynamical core usually has filter in the polar regions to filter out small scales
- Aside: Lat-lon grid is "optimal" for minimizing zonal flow errors! ...
 when grid is no longer aligned errors get rather large

Jablonowkski steady-state test case



Jablonowkski steady-state test case

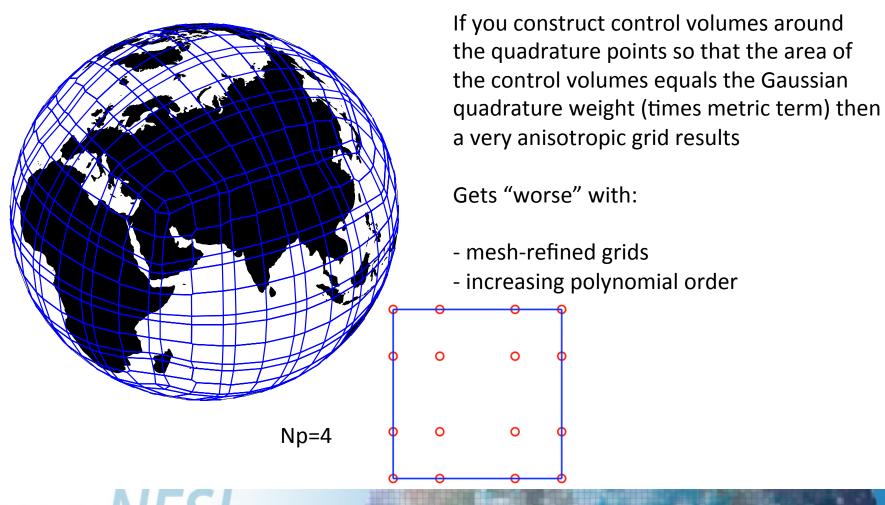


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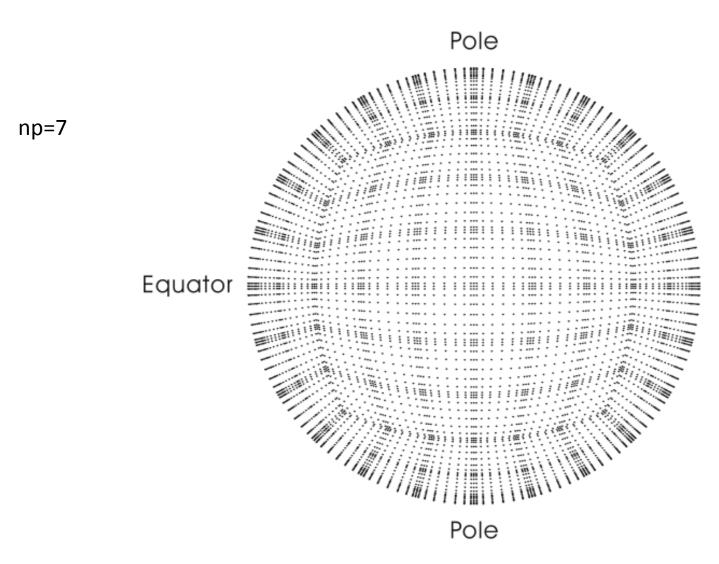


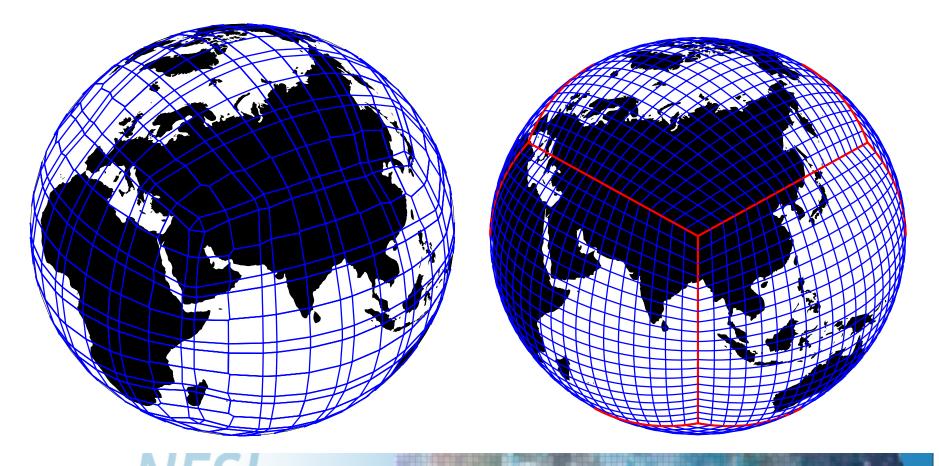
Figure 1. An orthographic view of the hexahedral grid points used in this study for NSEAM. Six elements on one face in one direction and 8th polynomial order of the basis functions are selected for this study. This horizontal

Kim et al. (2008)

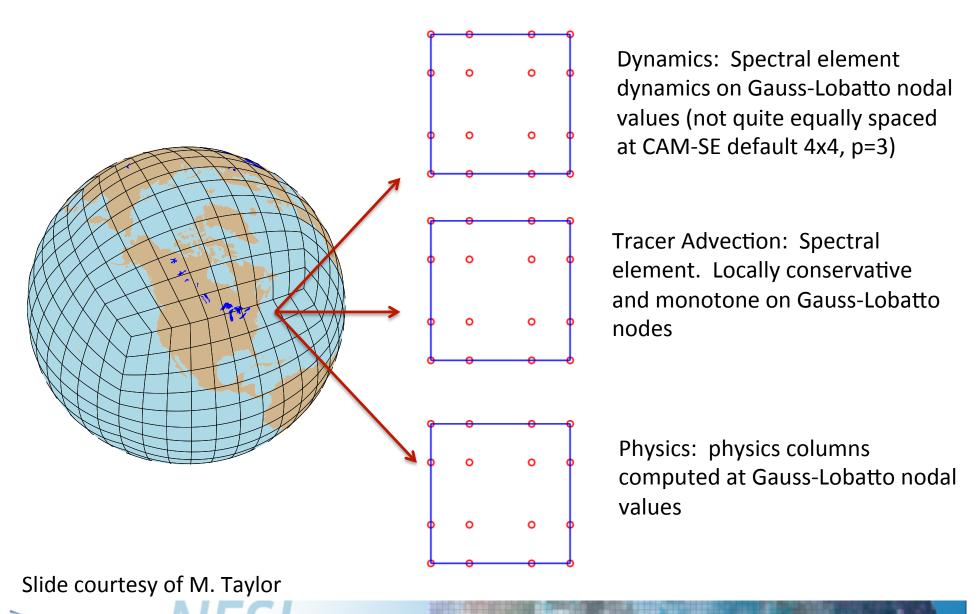
Separate physics-dynamics grids?

Current physics/"coupler" grid

Finite-volume equi-angular gnomonic grid

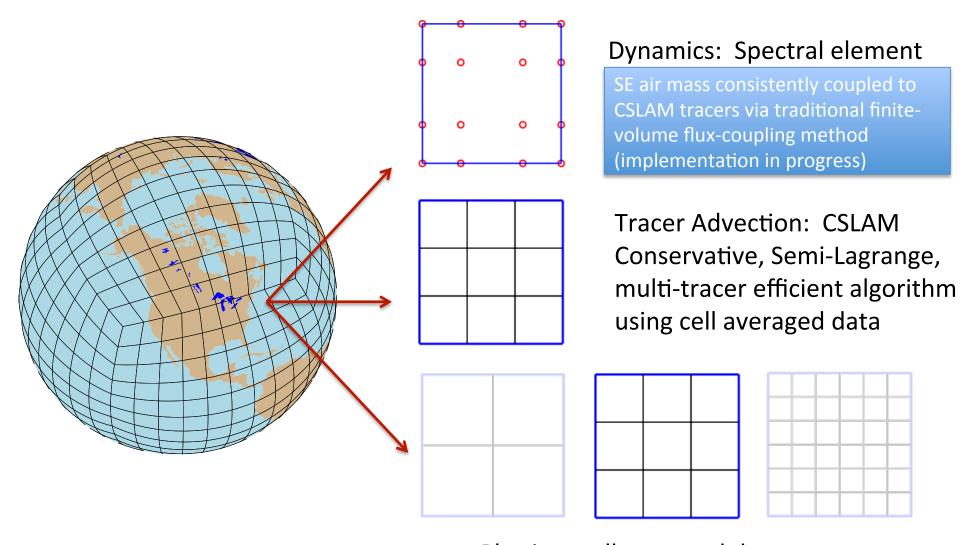


CAM-SE "default" NE30NP4 configuration



NCAR Earth System Laboratory

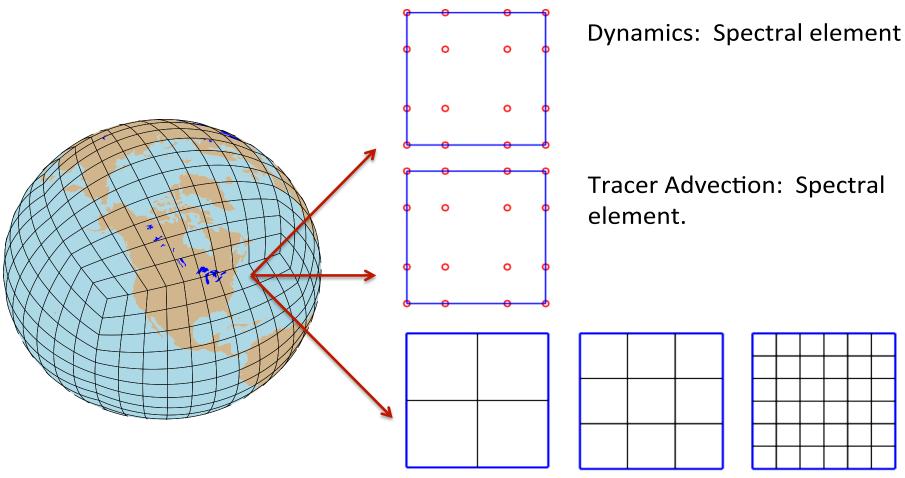
CAM-SE/CSLAM physics grid



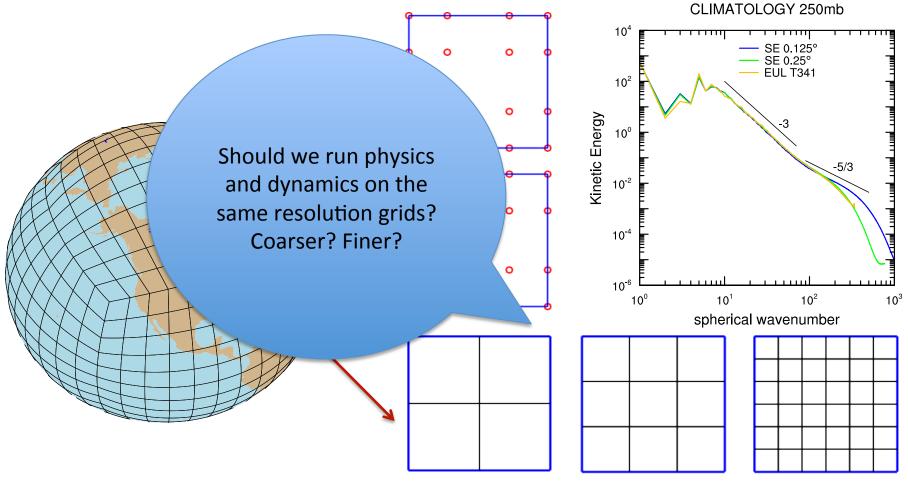
Slide courtesy of M. Taylor

Physics: cell averaged data.

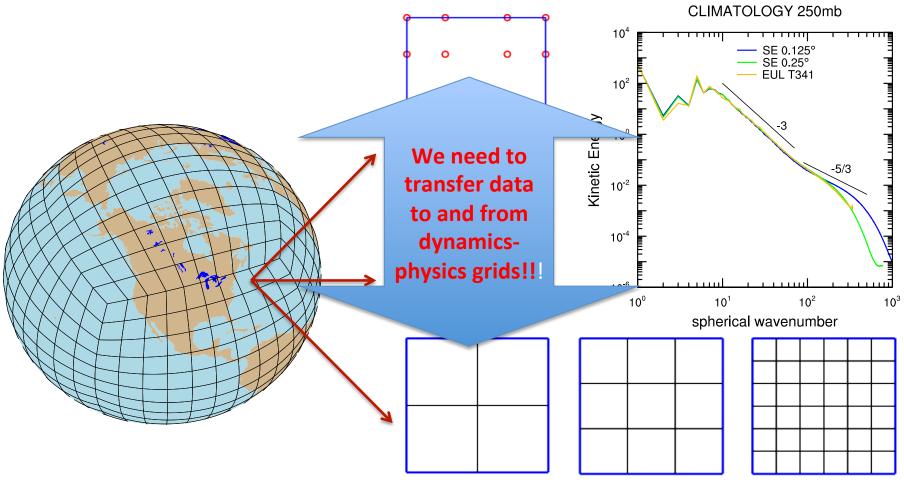




Physics: physics columns computed with cell averaged data. Physics can use a coarser, identical, or finer resolution grid

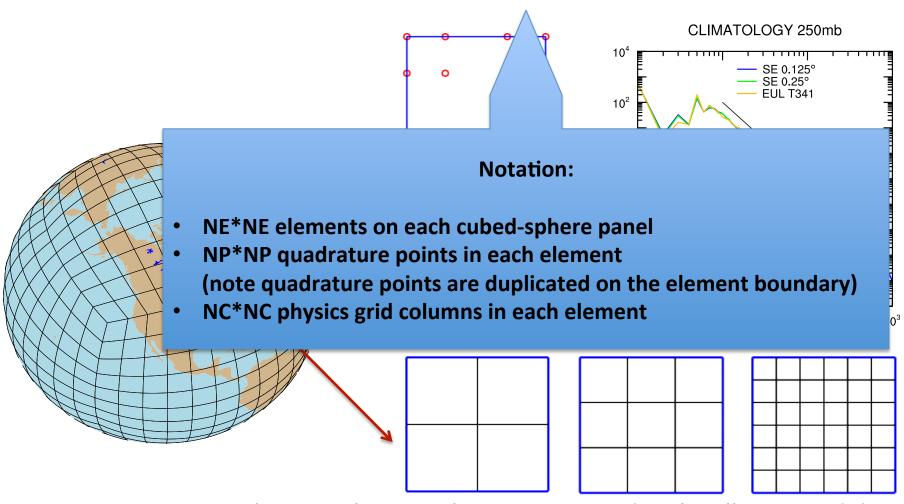


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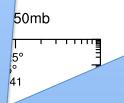


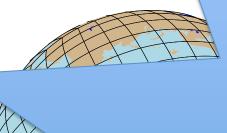
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CAM-SE physics grid NE30NP4NC3

guration







Separating physics and dynamics grids was a major software engineering task in CAM — affected many parts of the code:

- history (output)
- initialization/restart
- Some parameterizations assumed grids were collocated
- Initially our results were terrible: it was due to passing updated state from physics to dynamics rather than tendencies (so even if physics did nothing the interpolation truncation errors were "passed" to dynamics ...)

with cell ave. or finer resolution grid

ed data.

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Slide courtesy of M. T

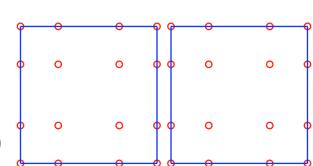
NCAR Earth System La

Interpolator properties: passing state to physics and returning tendencies to dynamics

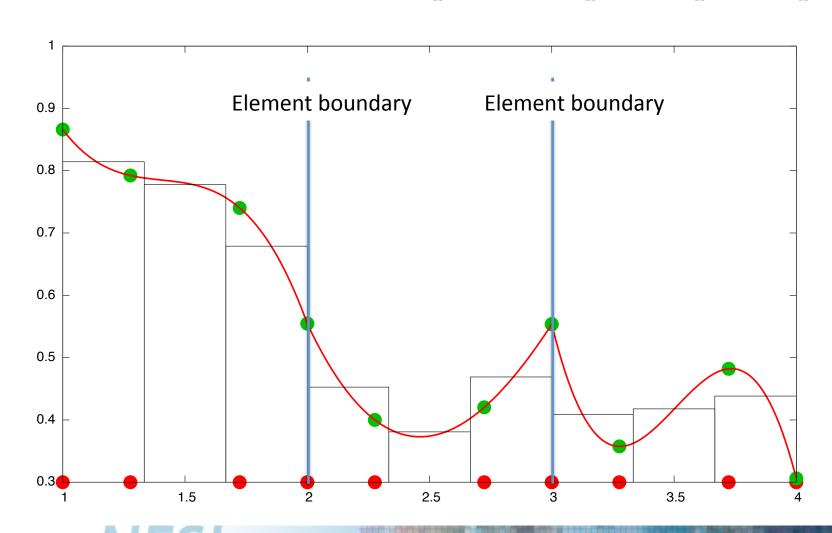
- Conservation (coupled climate modeling)
- Shape-preservation (in particular, no negatives)
- Preserve tracer correlations (important for coupling with chemistry)
- Consistent (preserves a constant)
- Other? Total energy?

Implementation constraints/limitations (not "physical" limitations):

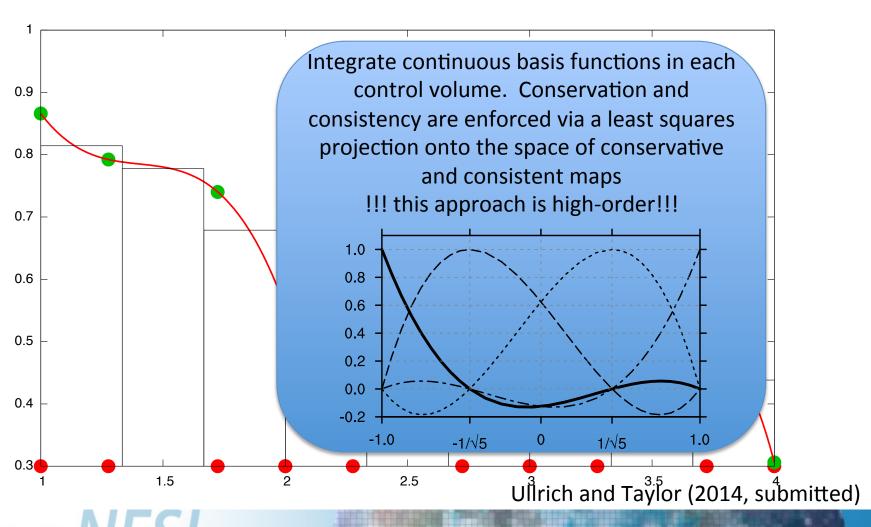
- Physics-grid must be a sub-grid of the element
 With some extra software engineering we can relax this constraint!
 (example application: mesh-refinement)
- To reduce MPI communication no halo exchange for physics-dynamics coupling except for boundary exchange at end of interpolation (could also be relaxed at the expense of computational cost)



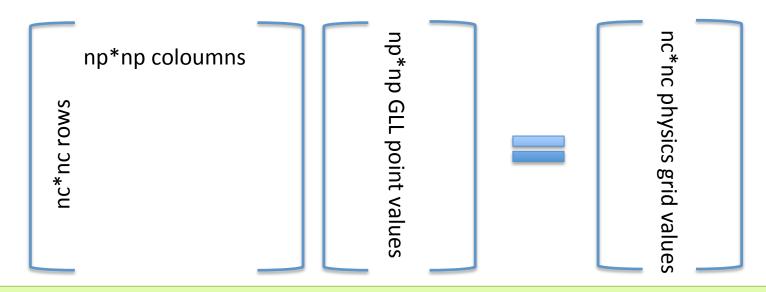
Passing state (v,T,q,...) to physics: For conservation we interpolate dp*u, dp*T, dp*q



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Passing state (v,T,q,...) to physics: For conservation we interpolate dp*u, dp*T, dp*q

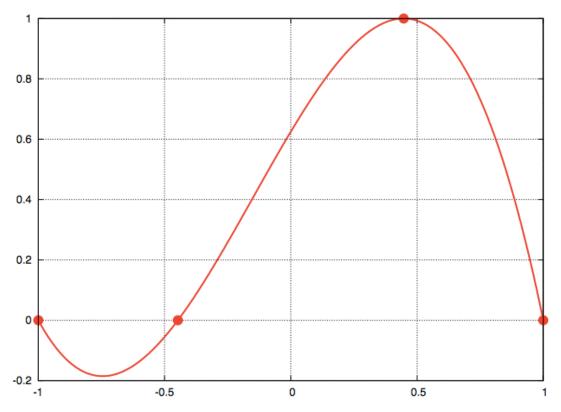


- Interpolation matrix can be pre-computed (it is a linear map)!!!
- After application of interpolation matrix there is a boundary exchange that averages point values on the element boundaries!
- Note: fundamentally different than finite-volume-type remapping where a halo is needed for the reconstruction

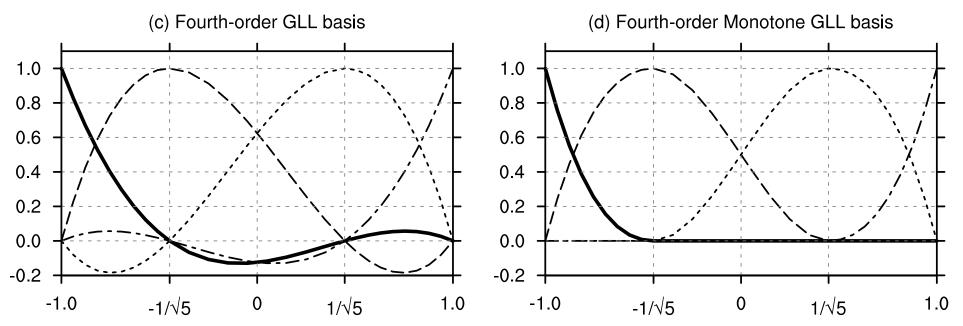
Ullrich and Taylor (2014, submitted)

Passing state (v,T,q,...) to physics: basis functions oscillatory!

Given GLL point values, $U_{j,k}(t) = \{0,0,1,0\}$ for k=0,...,3, the Lagrange "reconstruction" is shown on the Figure below:



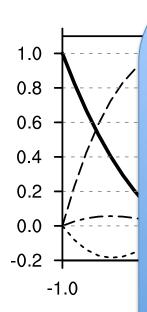
Monotone linear map



Monotonicity is enforced via a two-step procedure.

- instead of the regular FEM basis functions we use a set of monotone basis functions (ones whose range is [0,1]).
- This would be sufficient except for the fact that the least squares projection onto conservative/consistent maps could produce some (small) negative values in the mapping coefficients. To fix that problem we then "linearly interpolate" between the conservative/consistent map and the simplest first-order conservative/ consistent/monotone map. This has roughly the effect of "borrowing mass" from other GLL nodes within the element.

Monotone linear map



Potential problem: a monotone linear map that does not have any knowledge of the GLL values (i.e. not flow dependent) can at most be 1st order!

Modification to Ullrich-Taylor algorithm:

Monotonic

instead function

This work
 conserv
 mapping or interest.

Since any linear combination of linear maps is conservative and consistent one may "optimally" blend the maps for shape-preservation ("FCT-like method")

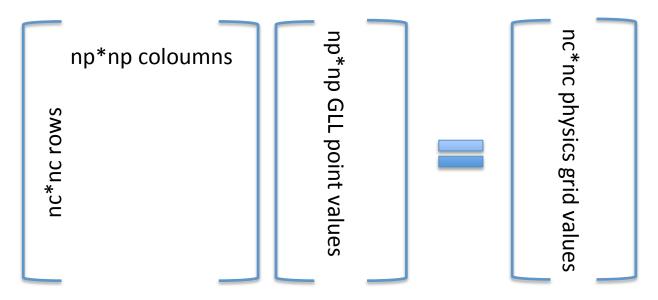
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Ullrich and Taylor (2014, submitted)

sis

1.0

"FCT" version of Ullrich-Taylor algorithm

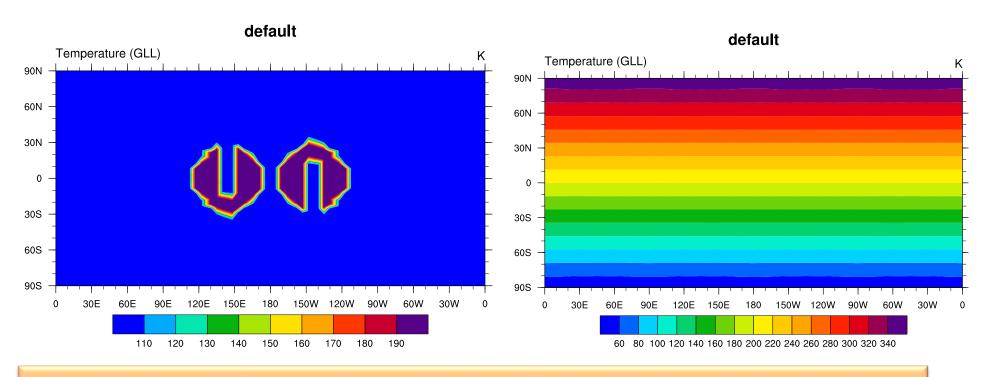


$$A_{\text{non-mono}} *GLL = PHYS_{\text{non-mono}}$$

$$A_{mono}$$
*GLL = PHYS_{mono}

$$\left[\alpha \text{ A}_{\text{mono}} + (1\text{-}\alpha) \text{ A}_{\text{non-mono}} \text{GLL}\right] = \text{PHYS}_{\text{mono}}$$
 where $\alpha = (\text{max(GLL)-PHYS}_{\text{non-mono}})/(\text{PHYS}_{\text{mono}} - \text{PHYS}_{\text{non-mono}})$ or
$$\alpha = (\text{min(GLL)-PHYS}_{\text{non-mono}})/(\text{PHYS}_{\text{mono}} - \text{PHYS}_{\text{non-mono}})$$

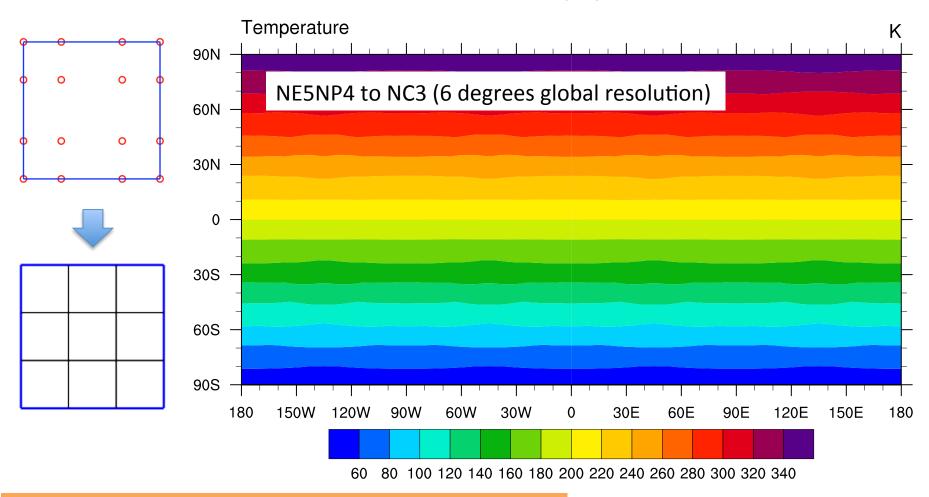
Dynamics to physics grid mapping



Properties we are looking for: Preserve smooth fields and at the same time not generate new extrema for rough distributions (and be mass-conservative and consistent)

Smooth field ("spherical harmonic")

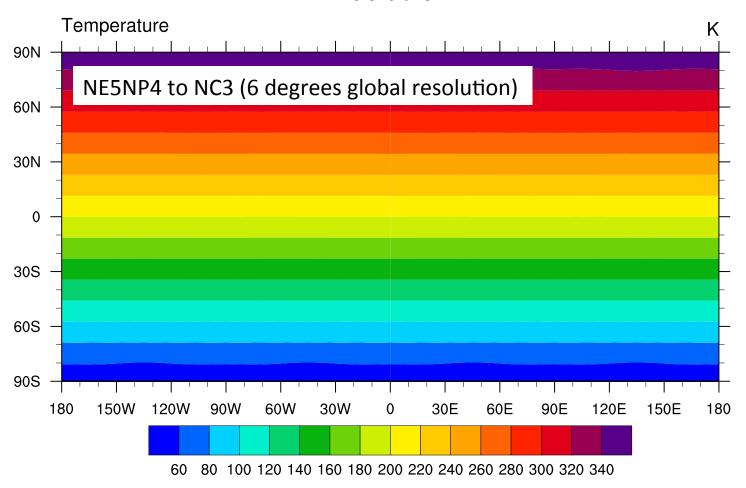
mono



1st order monotone map (not flow dependent): see grid

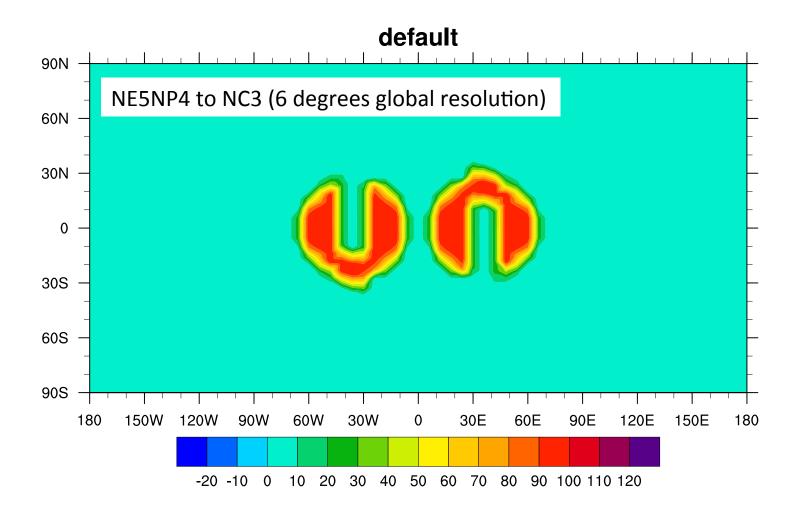
Smooth field ("spherical harmonic")

default



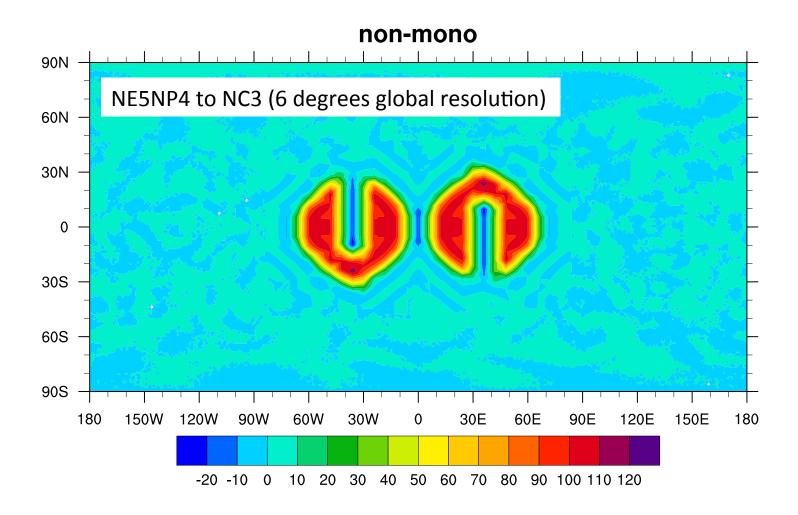
Optimally blend conservative and monotone map

Rough field ("slotted cylinder")



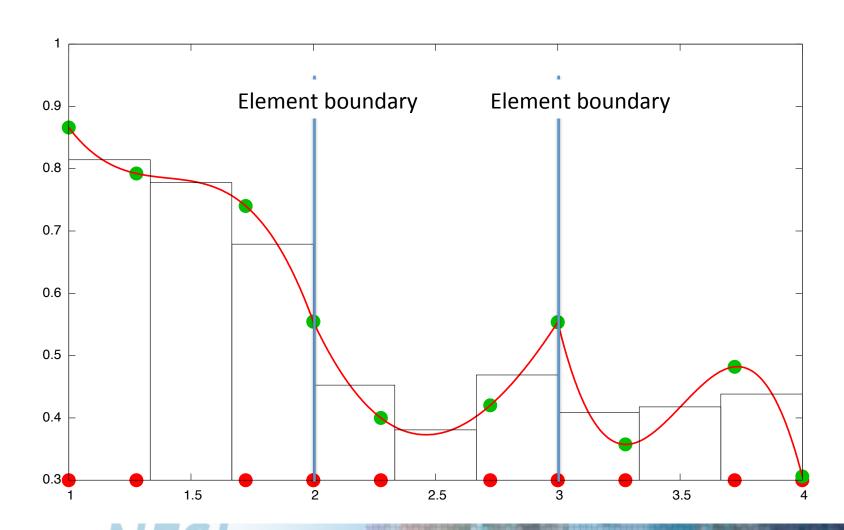
Optimally blend conservative and monotone map

Rough field ("slotted cylinder")



Non-monotone conservative

Passing tendencies (fv,fT,fq,...) to dynamics: Use a 1st-order, shape-preserving, conservative linear map



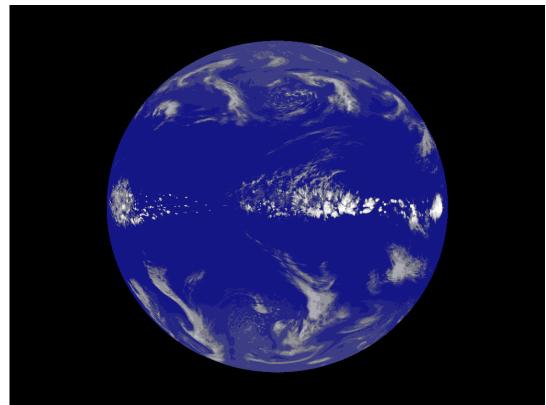




CAM4 forcing: Aqua-planet

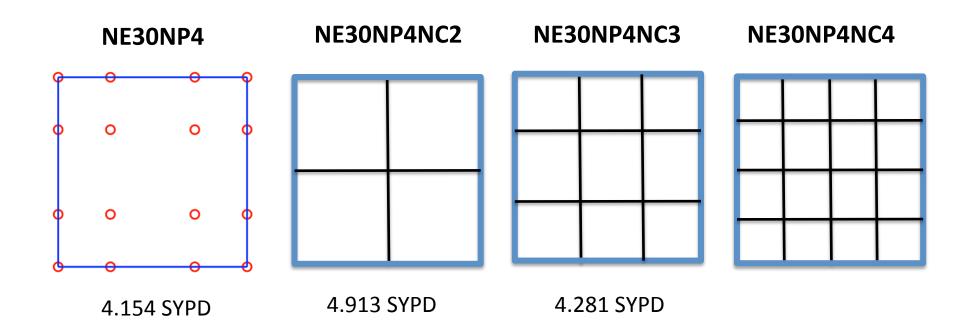
Atmospheric model with complete parameterization suite Idealized surface: no land (or mountains), no sea ice specified global sea surface temperatures everywhere

=> Free motions, no forced component



Why CAM4? More resolution sensitivity than CAM5 (and it is cheaper!)

Configurations

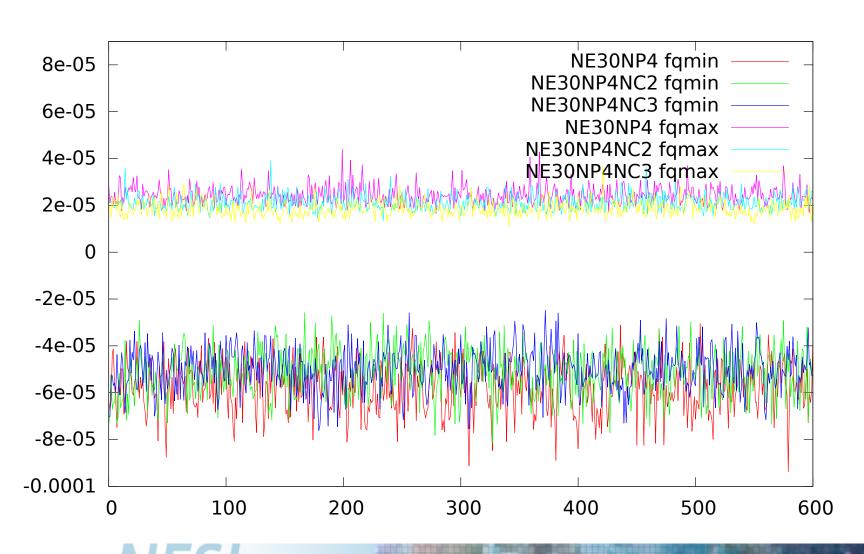


Efficiency measures in SYPD (= simulated years per day) on 2096 processors with I/O.

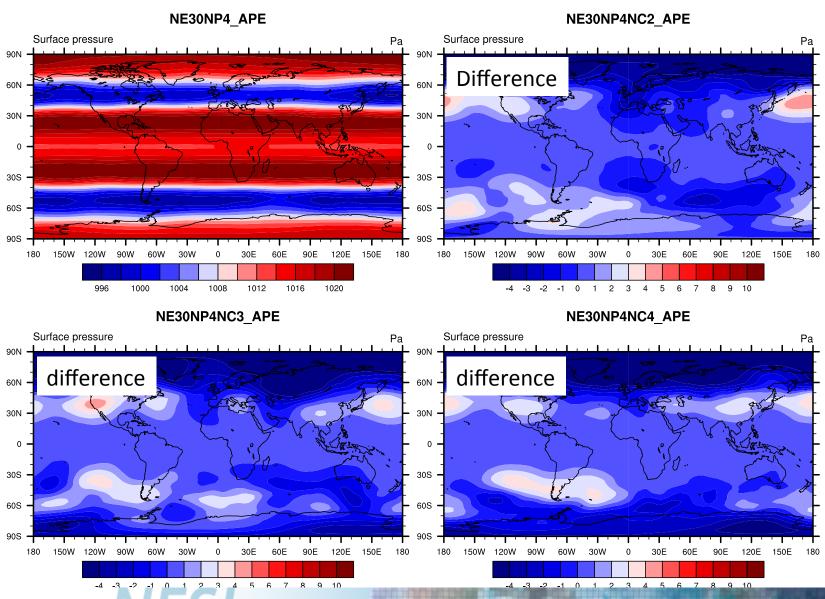
Data mapped to 3° lat-lon grid for analysis

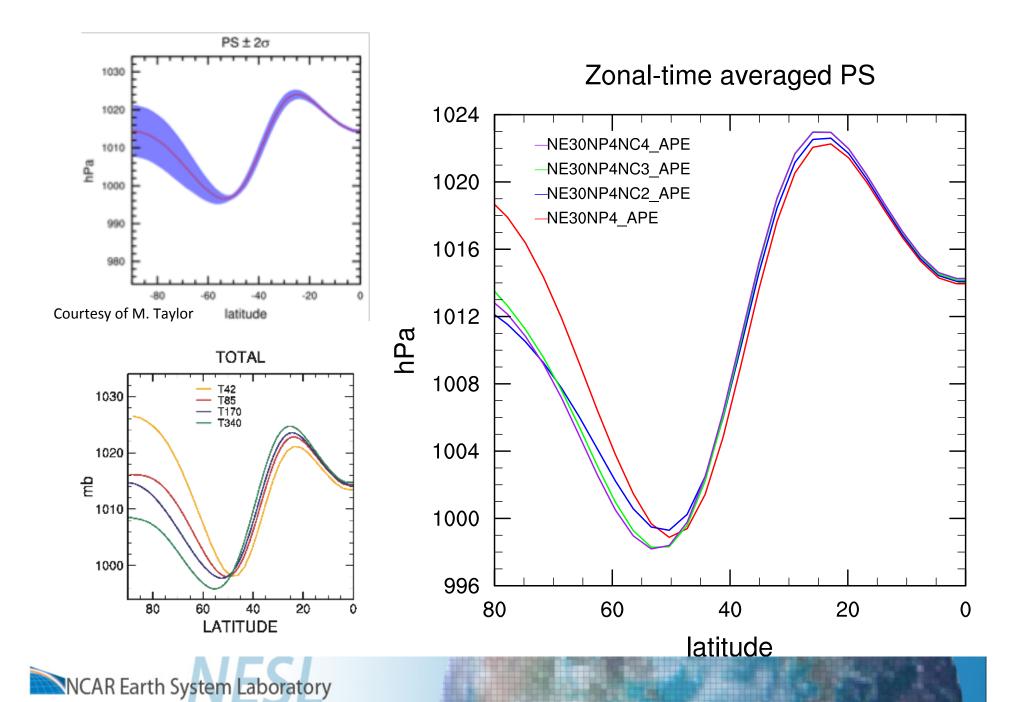
Length of simulations: 30 months

Min/max moisture forcing

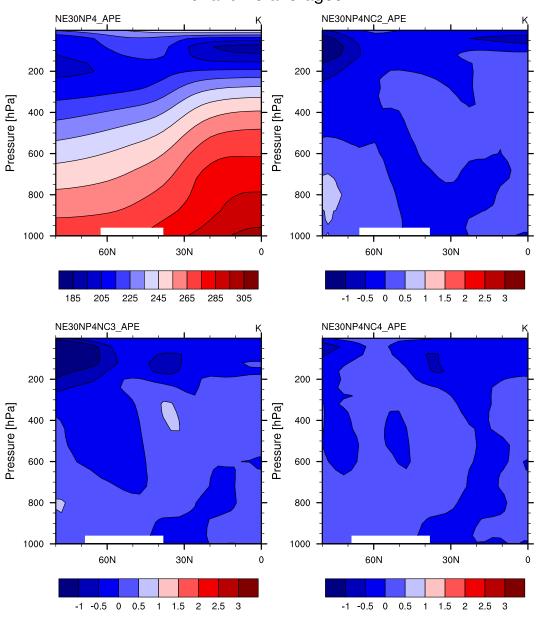


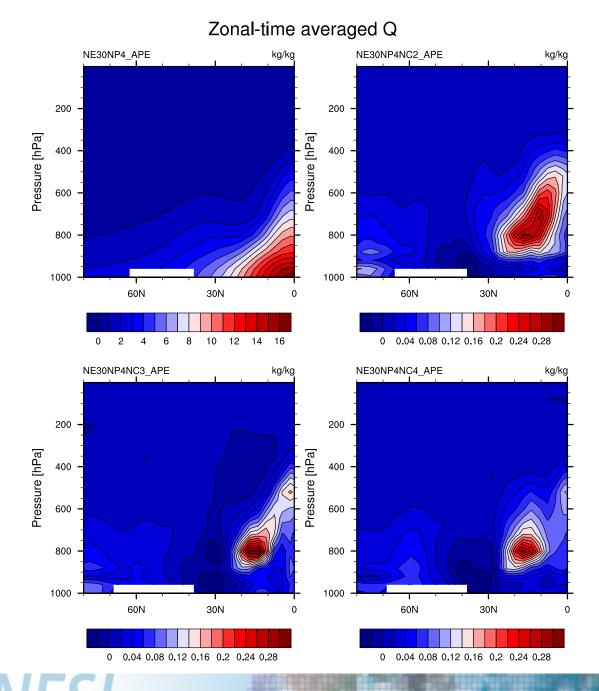
Time averaged PS



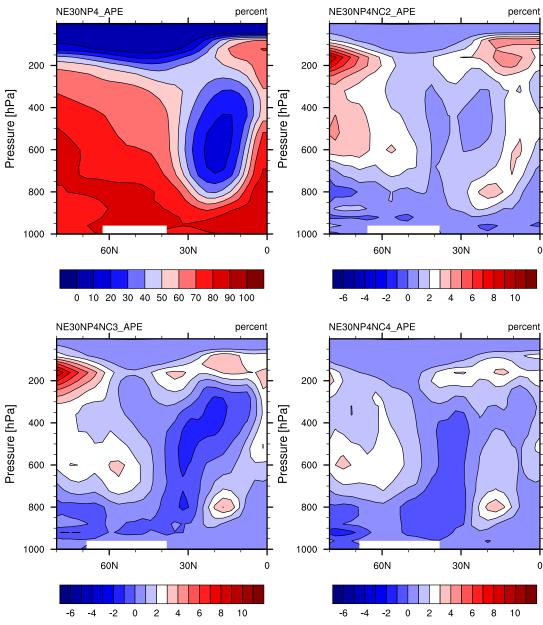


Zonal-time averaged T

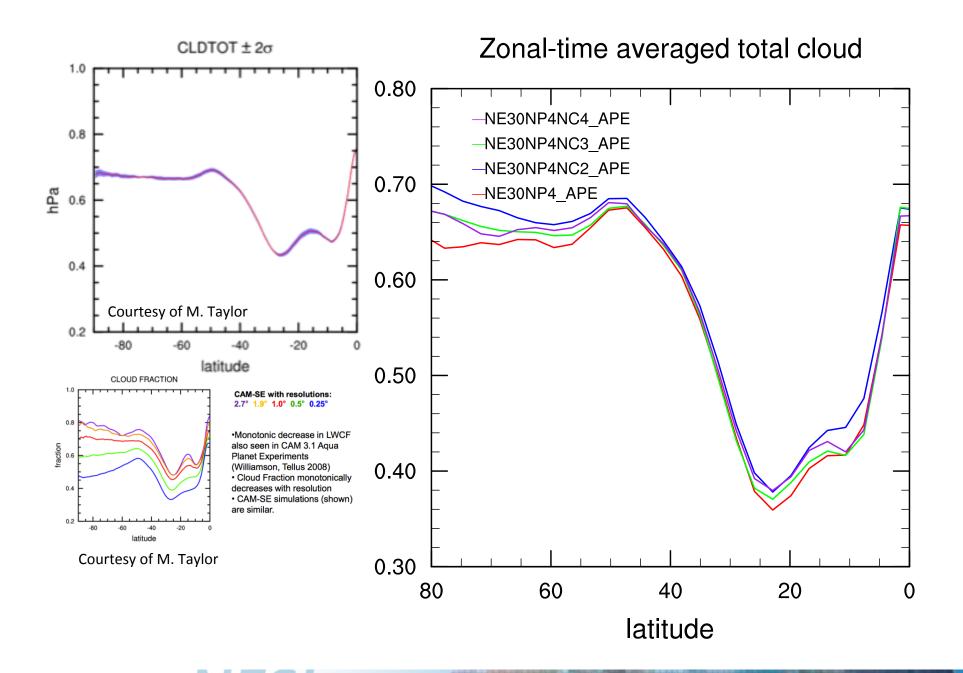




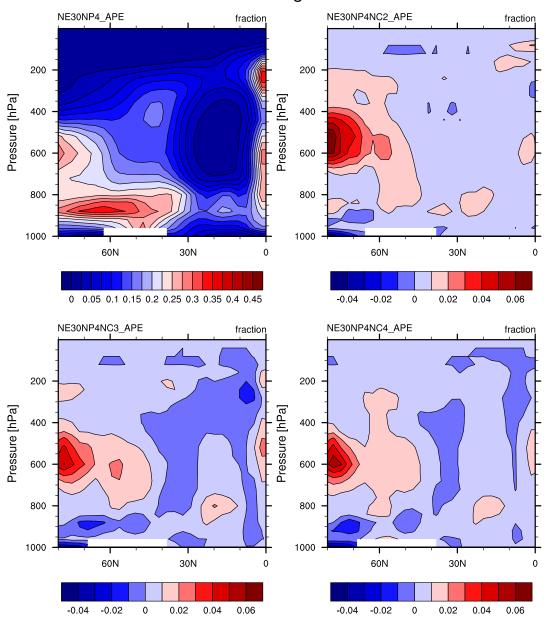
Zonal-time averaged RELHUM



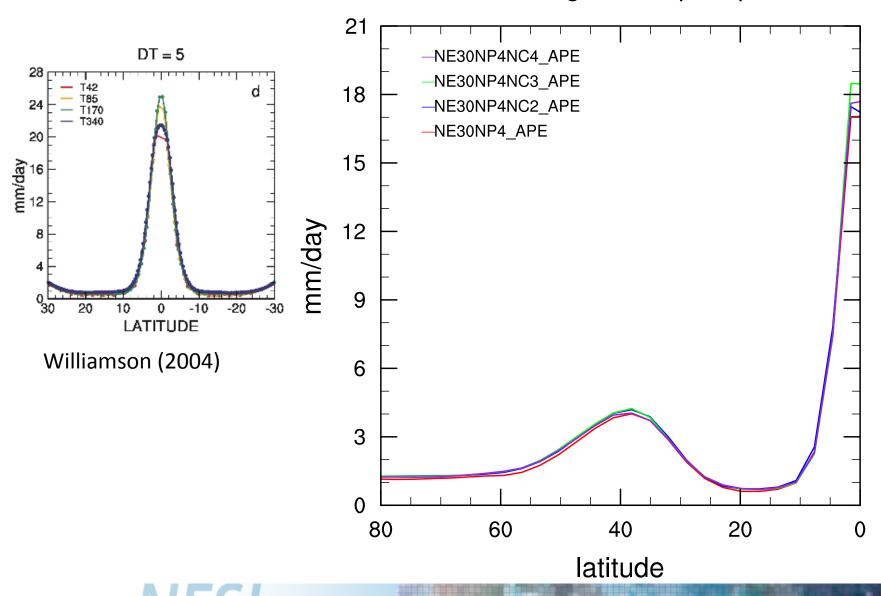
RELHUM = Relative humidity



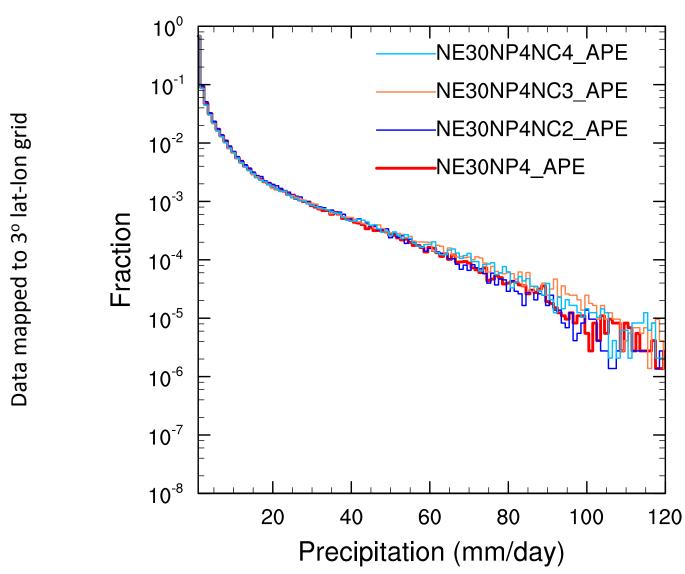
Zonal-time averaged CLOUD

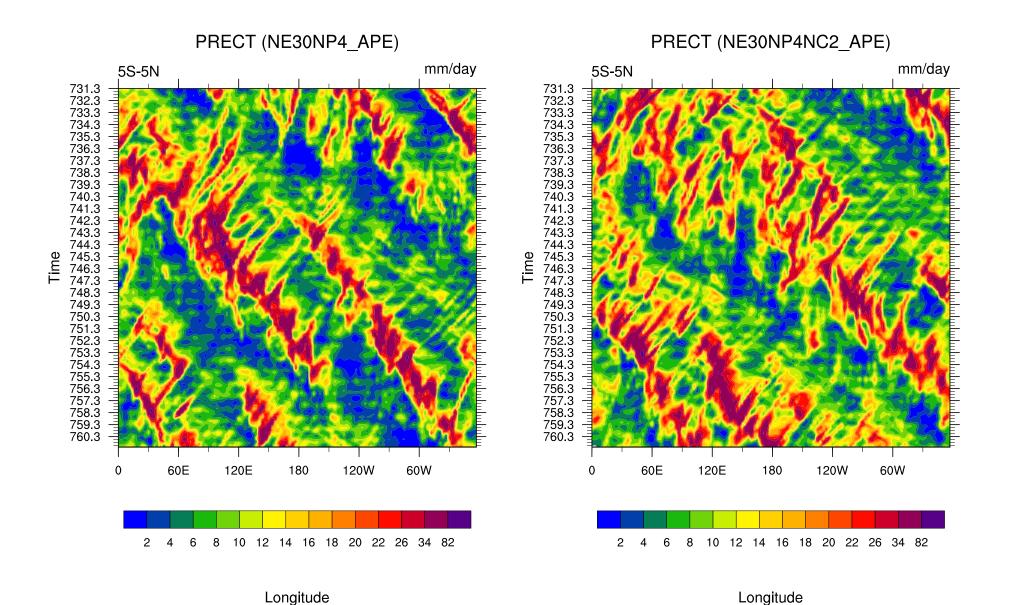


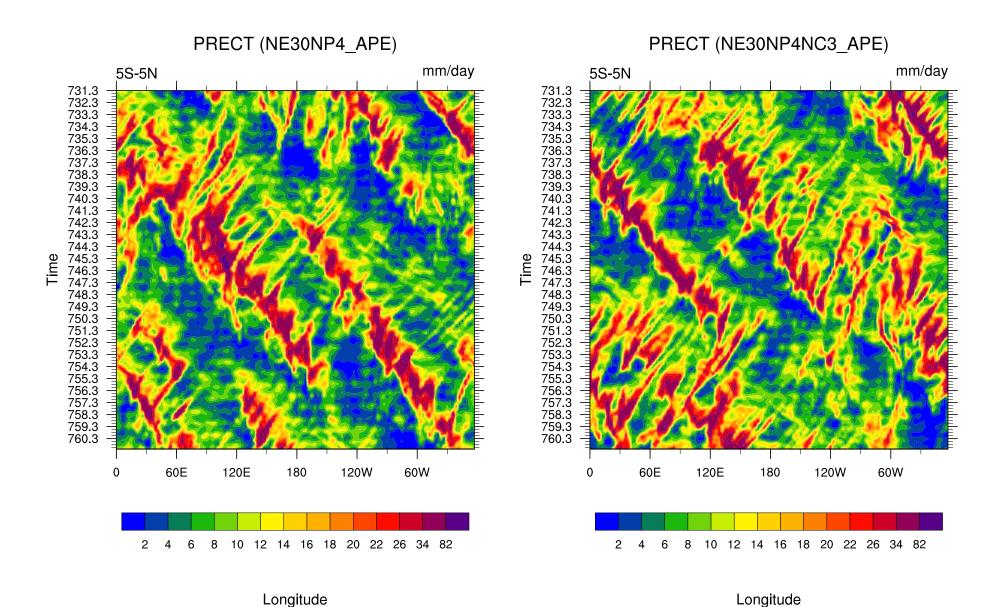
Zonal-time averaged total precipitation rate

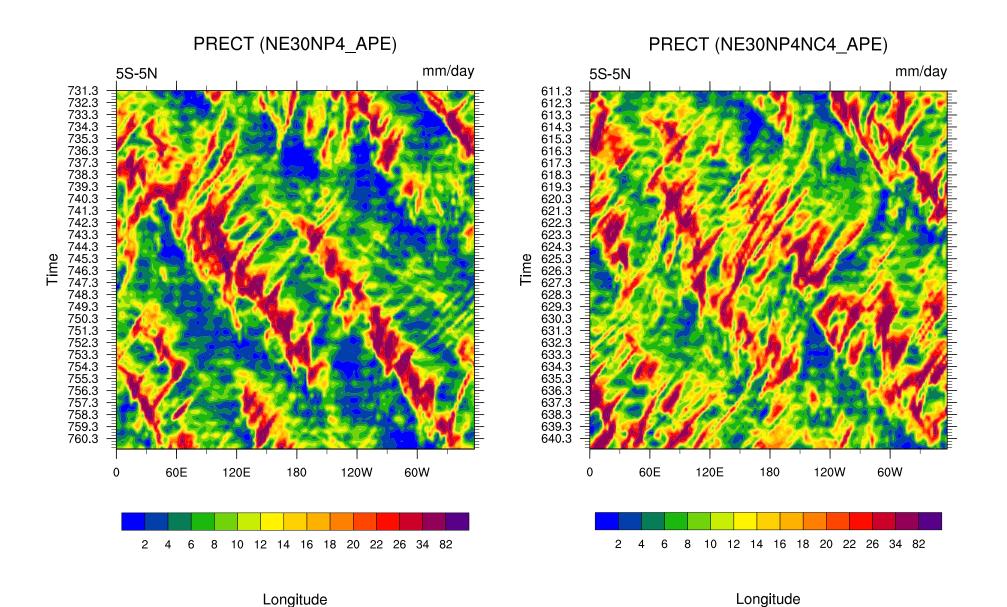


PDF
PRECT (30 month simulation - 6h data)





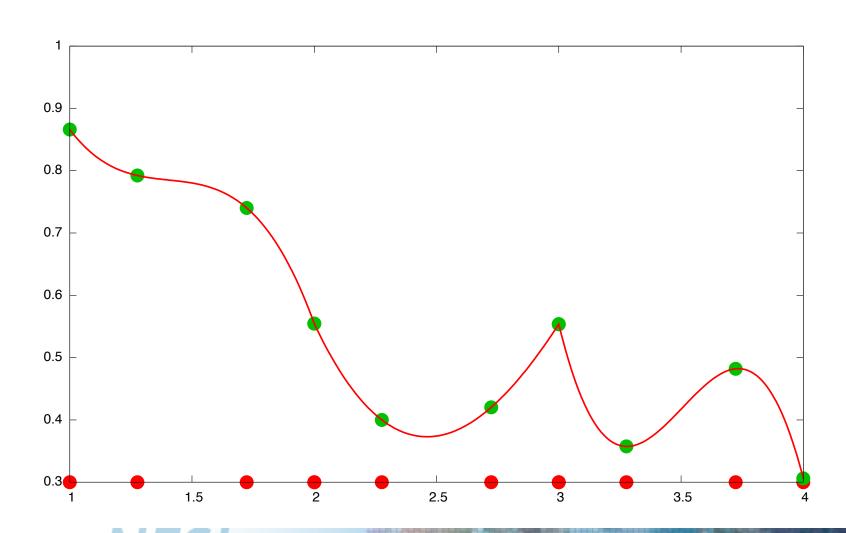




Stationary grid scale forcing

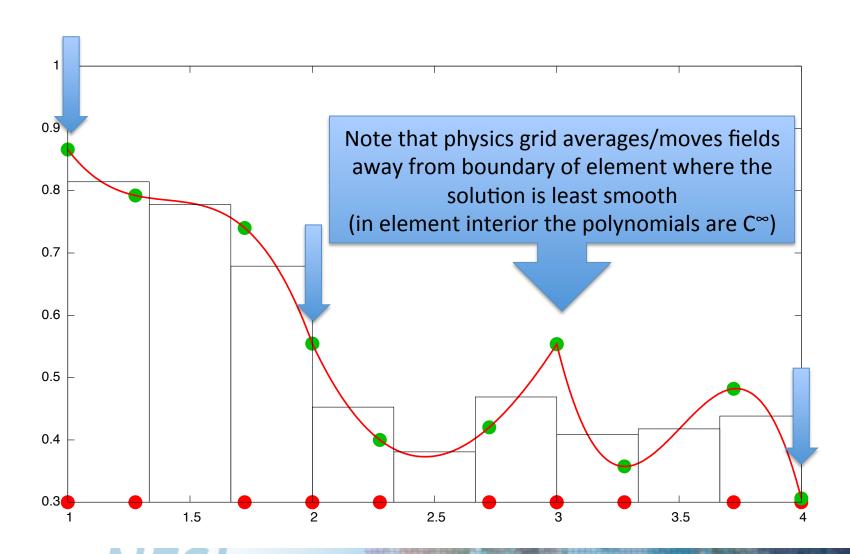


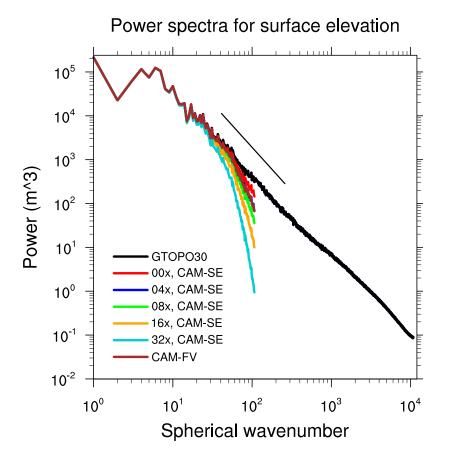












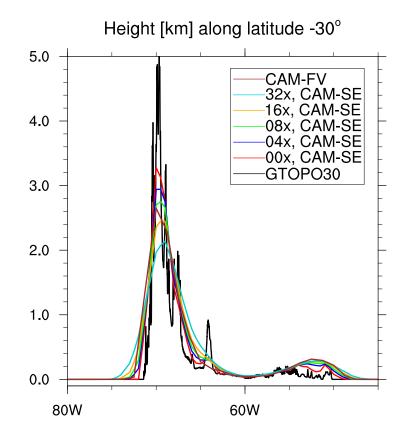
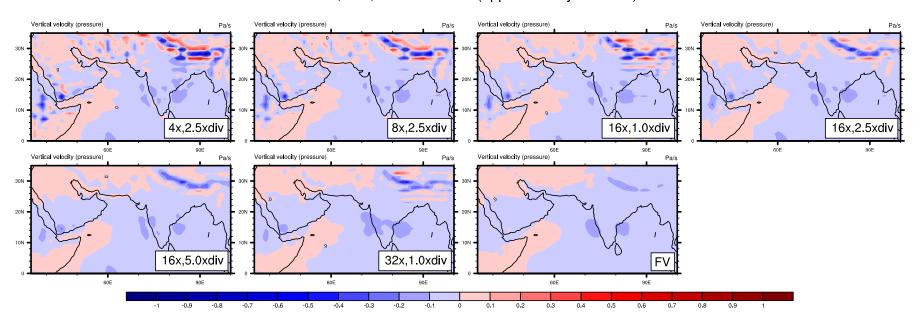


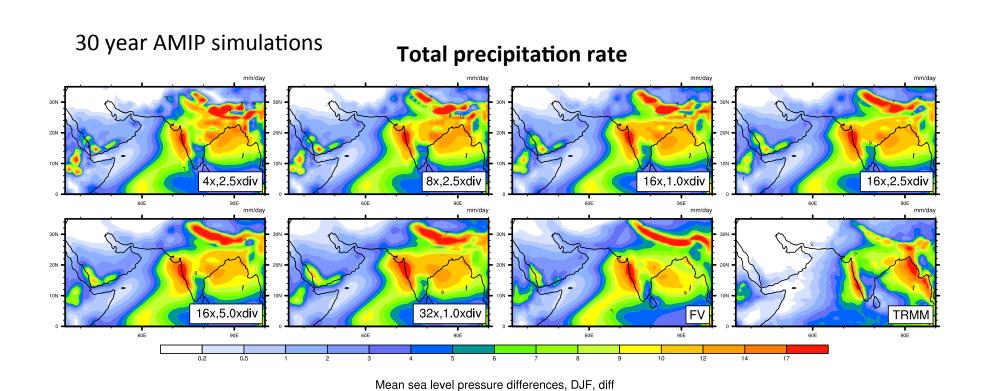
Figure 2. Surface elevation in kilometers for a cross section along latitude 30° S (through Andes mountain range) for different representations of surface elevation. The labeling is the same as in Figure

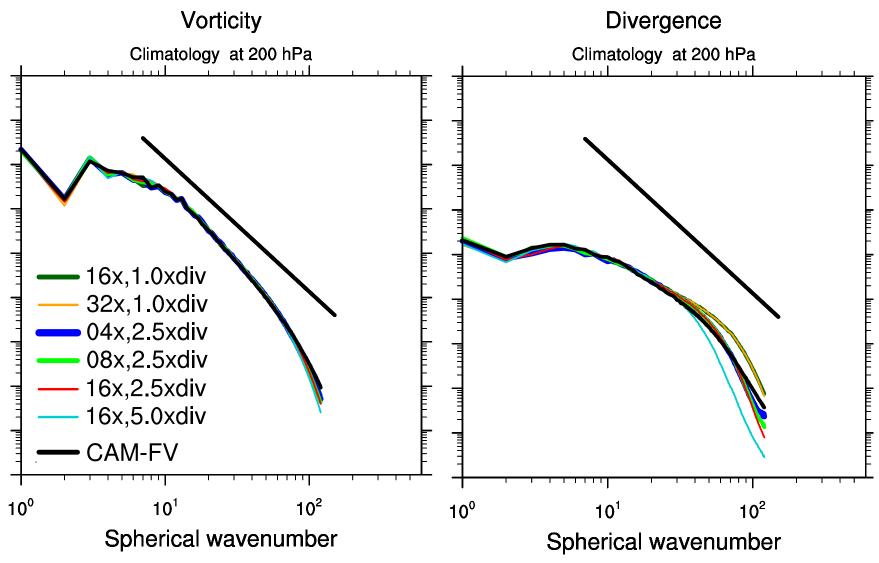
30 year AMIP simulations

OMEGA, JJA, model level 16 (approximately 323 hPa)

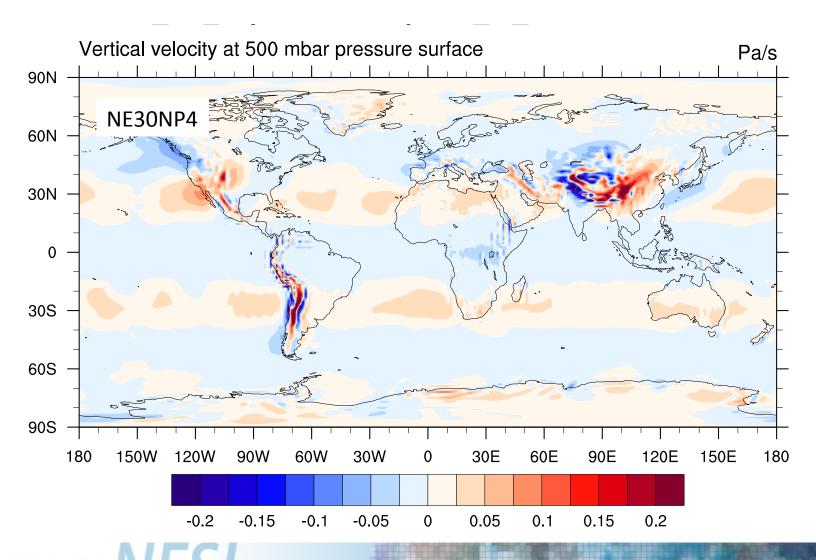


Notation: 2.5xdiv = 2.5 times more divergence damping than vorticity damping

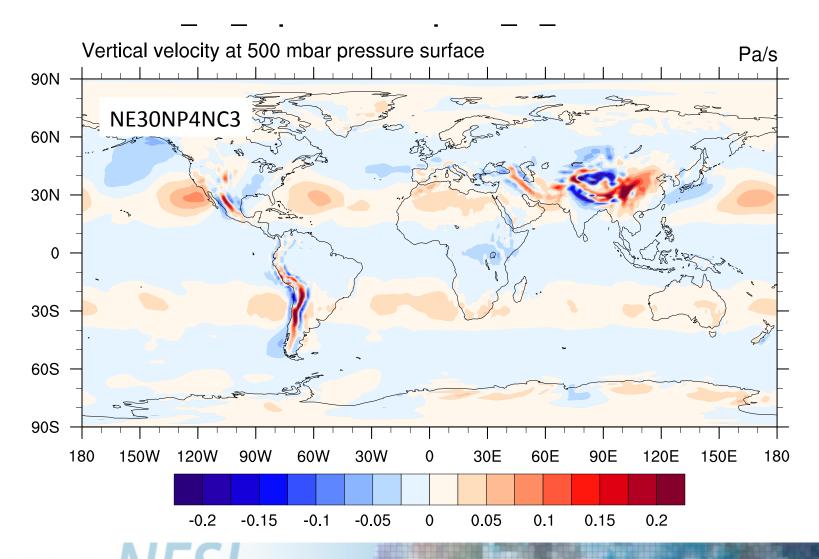




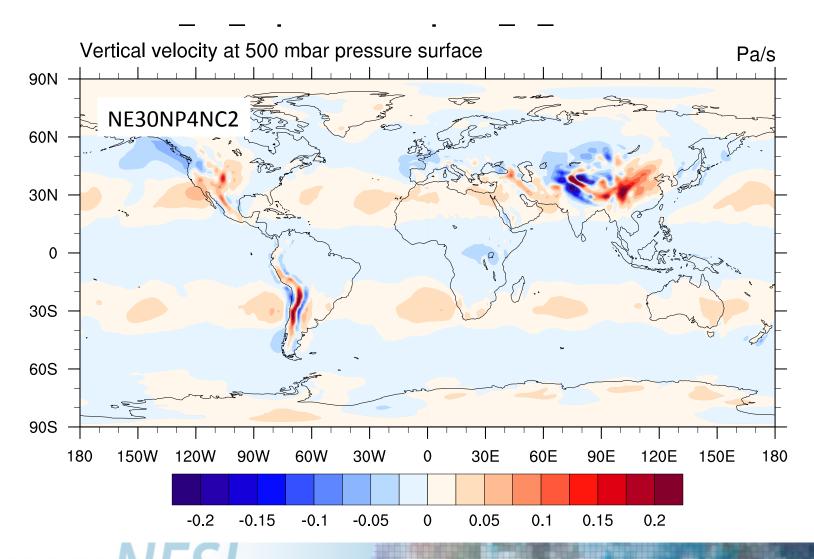
Held-Suarez with topography



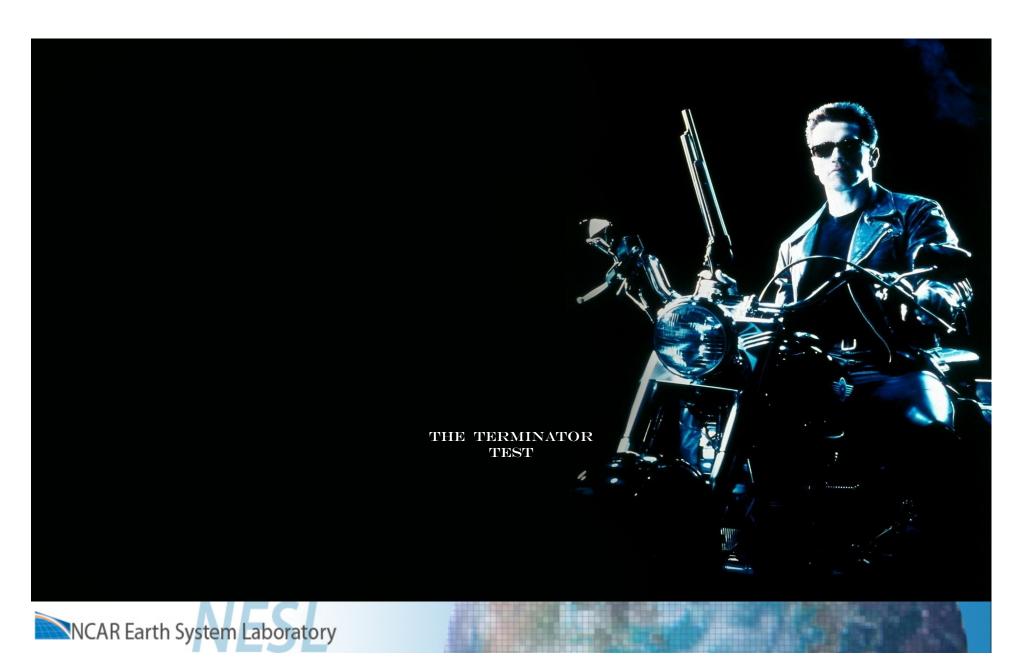
Held-Suarez with topography



Held-Suarez with topography



Aside

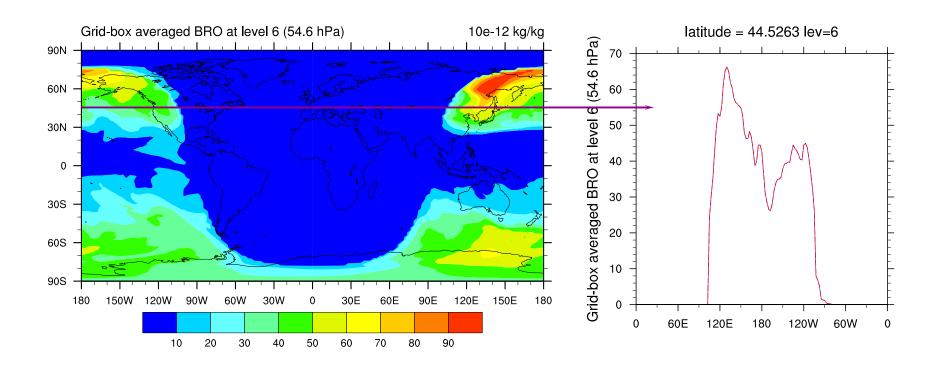


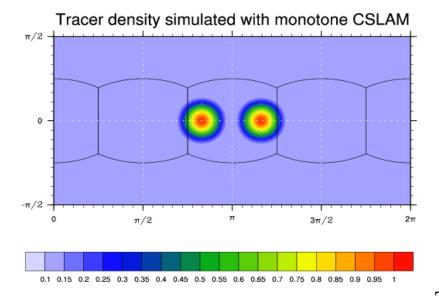
Go a step beyond inert transport testing, that is, add non-linear forcing to idealized flow problem!

At the same time keep things simple enough to be able determine/understand cause and effect

An option: simplified chemical reactions (right-hand side is products of mixing ratios)

"Inspiration": Photolysis driven chemistry







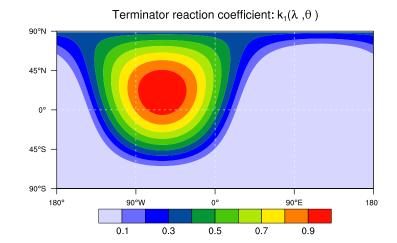
The kinetic equations corresponding to the above system (equations (2) and (1)) are given by

$$\frac{DCl}{Dt} = 2k_1Cl_2 - 2k_2ClCl, \tag{4}$$

$$\frac{D\text{Cl}_2}{Dt} = -k_1\text{Cl}_2 + k_2\text{Cl}\,\text{Cl},\tag{5}$$

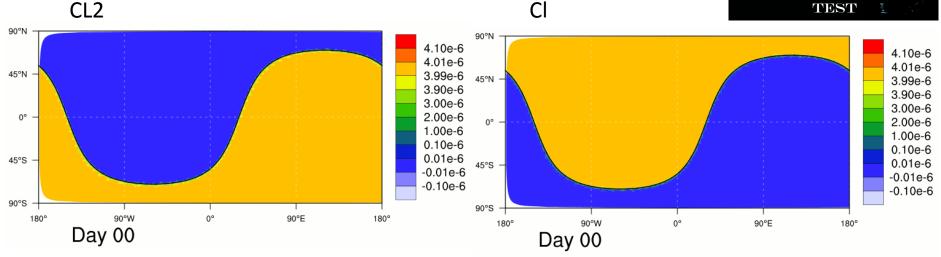
where D/Dt is the material (or total) derivative $D/Dt = \partial/\partial t + \mathbf{v} \cdot \nabla$ and \mathbf{v} is the wind vector. It is easily verified that the weighted sum of Cl and Cl₂ is conserved along characteristics of the flow

$$\frac{D\mathrm{Cl}_y}{Dt} = \frac{D}{Dt} \left[\mathrm{Cl} + 2\mathrm{Cl}_2 \right] = 0. \tag{6}$$



The terminator 'toy'-chemistry test: A simple tool to assess errors in transport schemes (Lauritzen et al, 2014, submitted to GMDD)



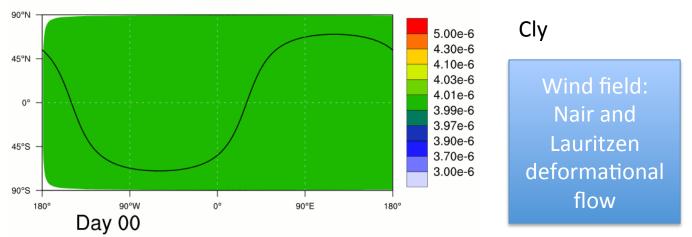


Non-linear "terminator-toy" chemistry:

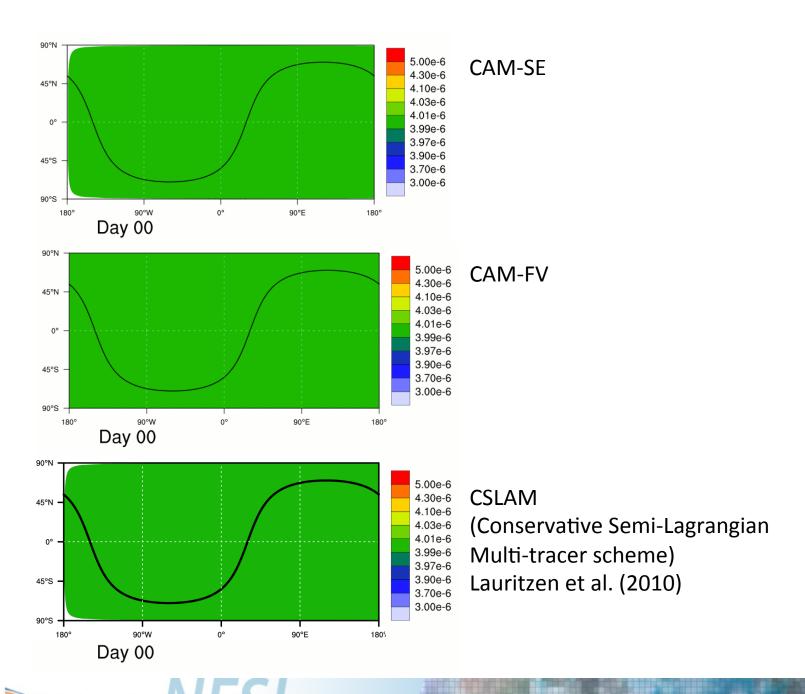
$$Cl_2 \rightarrow Cl + Cl : k_1$$

$$Cl + Cl \rightarrow Cl_2 : k_2$$

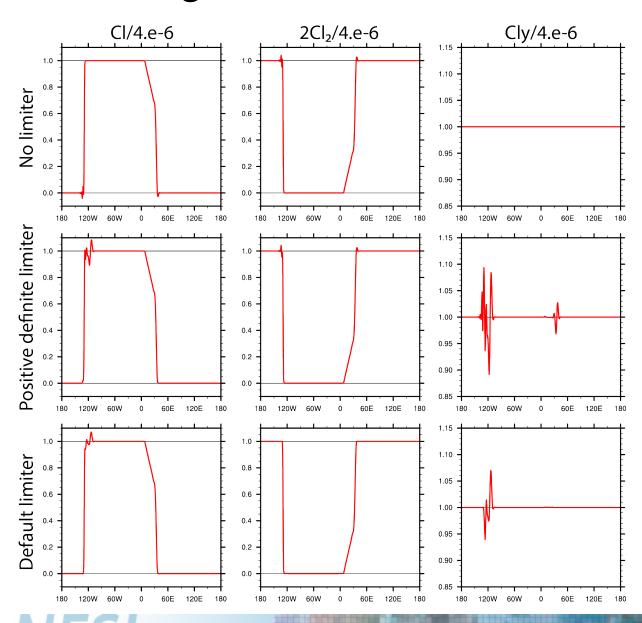
Exact solution: $Cl+2*Cl_2 = constant$



Errors are due to non-conservation of linear correlations by the limiter (and physics-dynamics coupling)



Testing limiters (with CAM-SE)



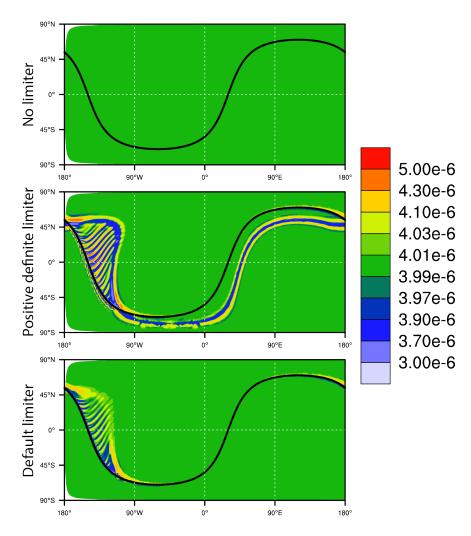


Figure 4. Contour plot of Cl_y at day 1 using CAM-SE in ftype=1 configuration where (upper) no limiter, (middle) positive definite limiter, and the default CAM-SE limiter is applied, respectively. The solid black line depicts the location of the terminator line. Note that the contour levels are not linear.

Simplified framework to test physics dynamics coupling

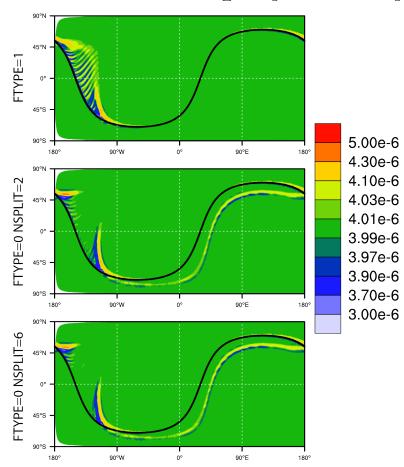
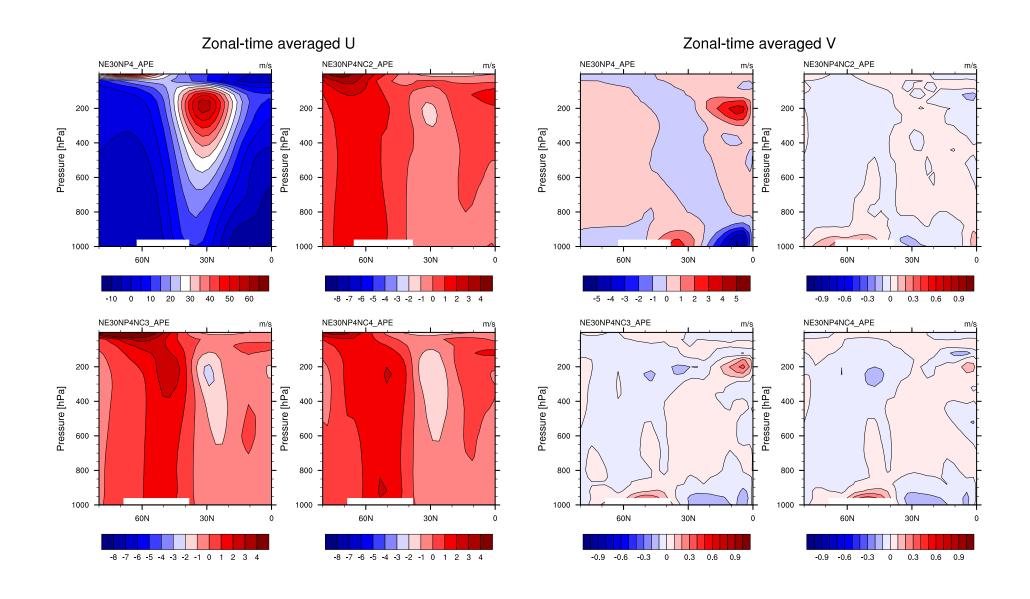


Figure 6. Contour plots of Cl_y at day 1 using CAM-SE based on (upper) ftype=1, (middle) ftype=0 and nsplit=3, and (lower) ftype=0 and nsplit=6, respectively. In all simulations the tracer time-step is constant $\Delta t_{tracer}=300s$.

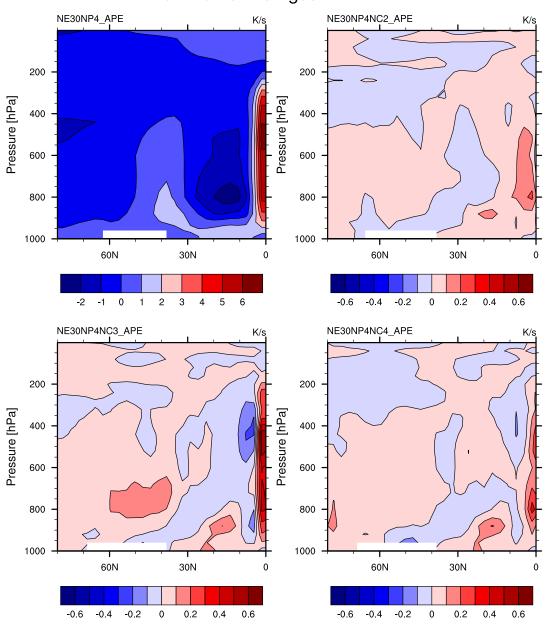
Algorithm 1 Pseudo-code explaining the different levels of subcycling and physics-dynamics coupling used in CAM-SE.

```
Outer loop advances solution \Delta t in time: for t=1,2,\ldots do  \text{Compute physics tendencies } F_i, i=\operatorname{Cl},\operatorname{Cl}_2  for ns=1,2,\ldots,nsplit do  \text{Update state with chemistry/physics tendencies: } C_i=C_i+\frac{\Delta t}{nsplit}\,F_i,\,i=\operatorname{Cl},\operatorname{Cl}_2  for rs=1,2,\ldots,rsplit do  \text{subcycling of tracer advection: } C_i=C_i+\frac{\Delta t}{nsplit\times rsplit}\,\mathcal{T}(C_i),\,i=\operatorname{Cl},\operatorname{Cl}_2  end for end for end for
```





Zonal-time averaged PTTEND



PRECC (30 month simulation - 6h data)

