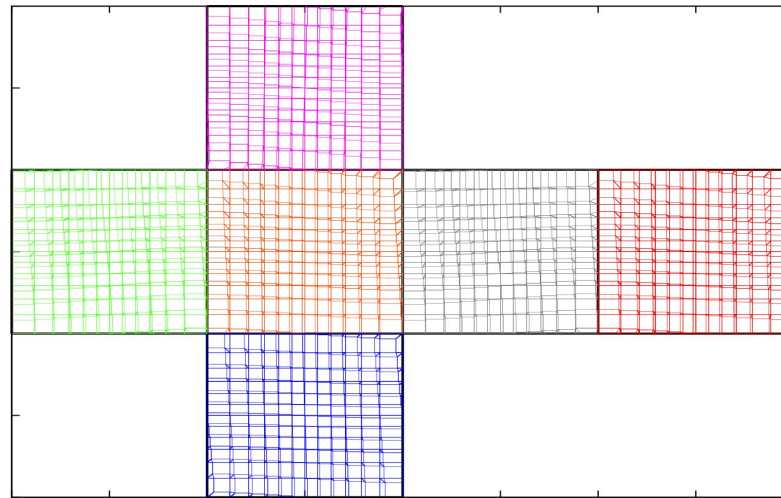
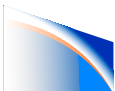


CAM-SE-CSLAM: Consistent finite-volume transport with spectral-element dynamics



Peter Hjort Lauritzen

**Atmospheric Modeling and Prediction Section (AMP)
Climate and Global Dynamics Laboratory (CGD)
National Center for Atmospheric Research (NCAR)**



NCAR

PDEs on the Sphere, KIAPS, Seoul, October 17-23, 2015

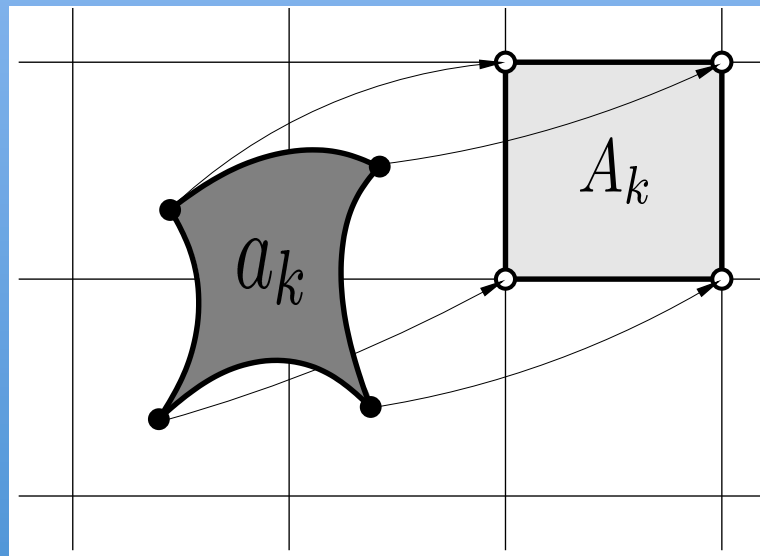


CAM-SE-CSLAM: Consistent finite-volume transport with spectral-

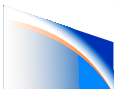
Consider the finite-volume Lagrangian form of continuity equation for air (pressure level thickness, Δp), and tracer (mixing ratio, q):

$$\int_{A_k} \psi_k^{n+1} dA = \int_{a_k} \psi_k^n dA, \quad \psi = \Delta p, \Delta p q, \quad (1)$$

where n time-level.



**No sources/
sinks**



Some requirements (desirable properties) for transport schemes intended for global climate/climate-chemistry applications:

1. Global (and local) Mass-conservation

If Δp is pressure-level thickness and q is mixing ratio, then the total mass

$$M(t) = \int_{\Omega} \Delta p q dA,$$

is invariant in time: $M(t) = M(t = 0)$ (no sources/sinks)

2. Shape-preservation

Scheme does not produce new extrema (in particular negatives) in q

3. Preservation of pre-existing functional relations between tracers

Transport scheme preserves $q_2 = f(q_1)$ (no sources/sinks)

4. Consistency

The continuity equations for air and tracers are coupled:

$$\int_{A_k} \Delta p_k^{n+1} dA = \int_{a_k} \delta p_k^n dA, \quad (2)$$

$$\int_{A_k} (\Delta p q)_k^{n+1} dA = \int_{a_k} (\delta p_k q)^n dA. \quad (3)$$

If $q = 1$ then (3) should reduce to (2).



Some requirements (desirable properties) for transport schemes in

Consistency is trivial if (2) and (3) are solved with the same numerical method, however, that is not always the case:

- “Off-line” chemistry: prescribed wind and mass fields from , e.g., re-analysis.
- “Online” applications where (3) is solved with a different numerical method than (2)

3. Preserving functional relations between tracers

Transport scheme preserves $q_2 = f(q_1)$ (no sources/sinks)

4. Consistency

The continuity equations for air and tracers are coupled:

$$\int_{A_k} \Delta p_k^{n+1} dA = \int_{a_k} \delta p_k^n dA, \quad (2)$$

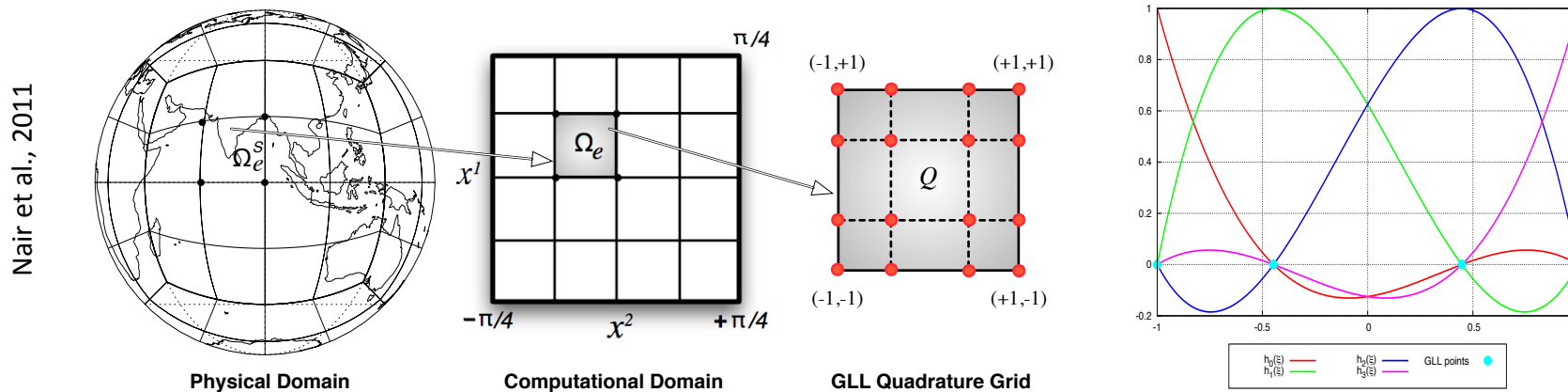
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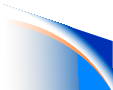


CAM-SE: NCAR Community Atmosphere Model with Spectral Elements dynamical core

Continuous Galerkin finite-element method (Taylor et al., 1997) on a cubed-sphere:



- 👍 Discretization is mimetic => mass-conservation & total energy conservation
- 👍 Conserves axial angular momentum very well (Lauritzen et al., 2014)
- 👍 Support static mesh-refinement and retains formal order of accuracy!
- 👍 Highly scalable to at least $O(100K)$ processors (Dennis et al., 2012)
- 👍 Competitive “AMIP-climate” (Evans et al., 2012)
- 👎 **Lower computational throughput for many-tracer applications**





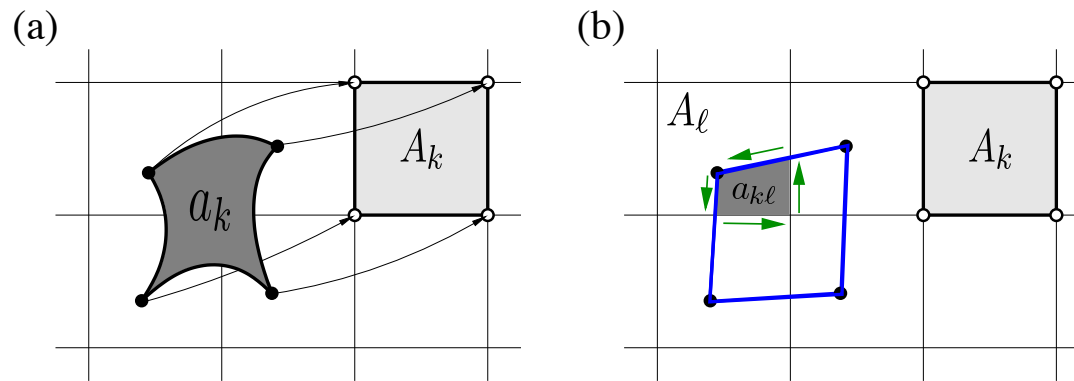
A way to accelerate tracer transport:



Basic formulation

Lauritzen et al. (2010), Erath et al. (2013), Erath et al. (2012)

Conservative Semi-Lagrangian Multi-tracer (CSLAM)



Finite-volume Lagrangian form of continuity equation for air (pressure level thickness, Δp), and tracer (mixing ratio, q):

$$\int_{A_k} \psi_k^{n+1} dA = \int_{a_k} \psi_k^n dA = \sum_{\ell=1}^{L_k} \left[\sum_{i+j \leq 2} c_\ell^{(i,j)} w_{k\ell}^{(i,j)} \right], \quad \psi = \Delta p, \Delta p q,$$

where n time-level, $a_{k\ell}$ overlap areas, L_k #overlap areas, $c^{(i,j)}$ reconstruction coefficients for ψ_k^n , and $w_{k\ell}^{(i,j)}$ weights.



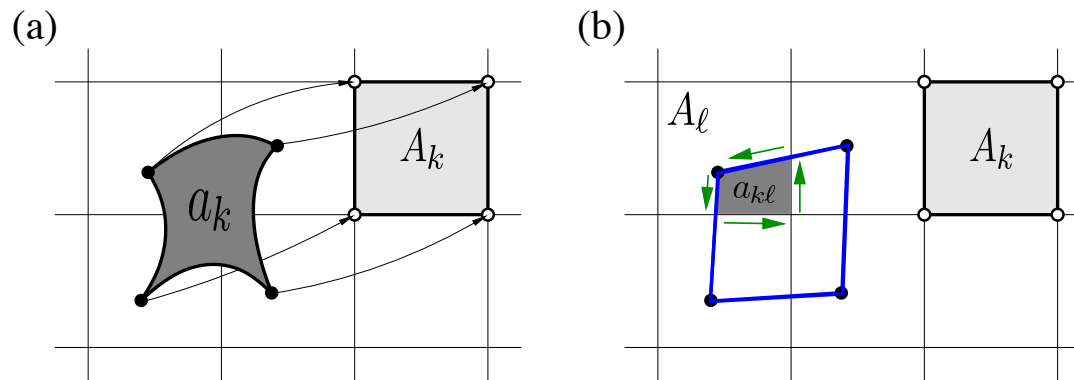
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$$\int_{A_k} \psi_k^{n+1} dA = \int_{a_k} \psi_k^n dA = \sum_{\ell=1}^{L_k} \left[\sum_{i+j \leq 2} c_{\ell}^{(i,j)} w_{k\ell}^{(i,j)} \right], \quad \psi = \Delta p, \Delta p q,$$

- Multi-tracer efficient: $w_{k\ell}^{(i,j)}$ re-used for each additional tracer (Dukowicz and Baumgardner, 2000).
- Scheme allows for large time-steps (flow deformation limited).
- Conserves mass, shape, linear correlations (Lauritzen et al., 2014).



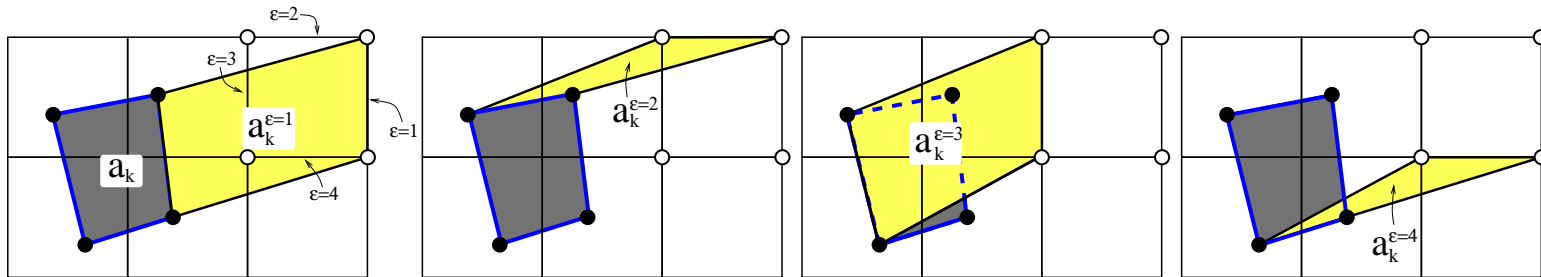
A way to accelerate tracer transport:



Basic formulation

Harris et al. (2010)

Flux-form CSLAM \equiv Lagrangian CSLAM



$$\int_{A_k} \psi_k^{n+1} dA = \int_{A_k} \psi_k^n dA - \sum_{\epsilon=1}^4 s_{kl}^{\epsilon} \int_{a_k^{\epsilon}} \psi dA, \quad \psi = \Delta p, \Delta p q.$$

where

- a_k^{ϵ} = 'flux-area' (yellow area) = area swept through face ϵ
- $s_{kl}^{\epsilon} = 1$ for outflow and -1 for inflow.

Flux-form and Lagrangian forms of CSLAM are equivalent (Lauritzen et al., 2011).

Coupling finite-volume semi-Lagrangian transport with spectral element dynamics

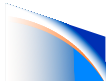
4. Consistency

The continuity equations for air and tracers are coupled:

$$\int_{A_k} \Delta p_k^{n+1} dA = \int_{a_k} \delta p_k^n dA, \quad (2)$$

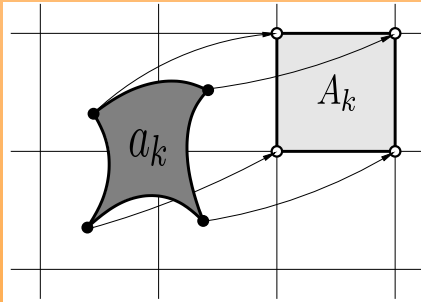
$$\int_{A_k} (\Delta p q)_k^{n+1} dA = \int_{a_k} (\delta p_k q)^n dA. \quad (3)$$

If $q = 1$ then (3) should reduce to (2).

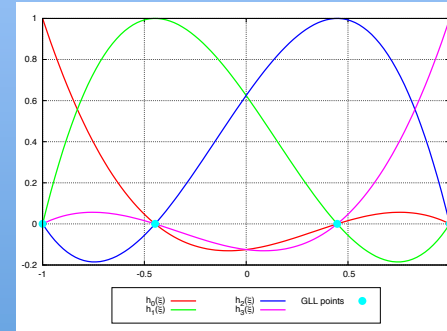


Coupling finite- in time element

Solved with semi-Lagrangian
scheme (CSLAM)
(max Courant number < 1)



Solved with spectral-element
Eulerian advection operator
(max Courant number < 0.3)



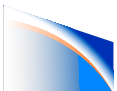
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If $q = 1$ then (3) should reduce to (2).

We need to couple without violating mass-conservation,
shape-preservation, and consistency



4. Consistency

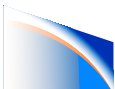
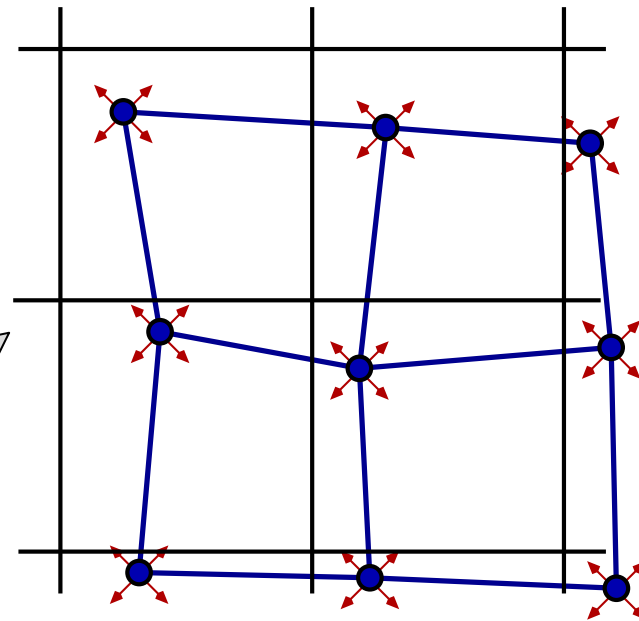
Find upstream area, a_k , so that CSLAM predicted mass field is equal to CAM-SE predicted mass field:

$$\Delta p_k^{n+1}(\text{CAM-SE}) = \frac{1}{\Delta A} \int_{a_k} \delta p_k^n dA (\text{CSLAM}), \quad (4)$$

If we choose to move departure points around so that (4) is fulfilled a global iteration problem results!



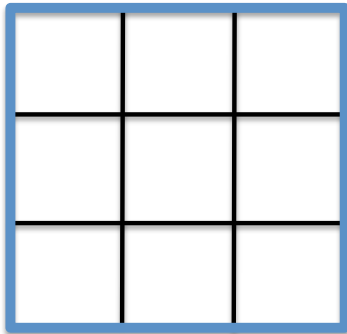
(and I am not sure it is well-posed!)



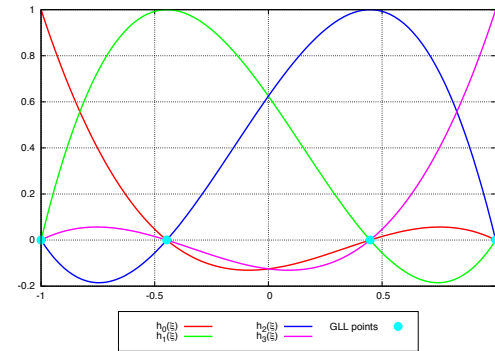
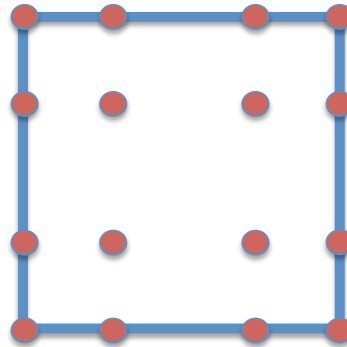
Solution: Cast problem in flux-form

- Spectral-element method does not operate with fluxes: Taylor et al. have derived a method to compute fluxes, $\mathcal{F}^{(SE)}$, through the CSLAM control volume faces! presented at ICMS conference in March, 2015.

CSLAM grid



GLL grid



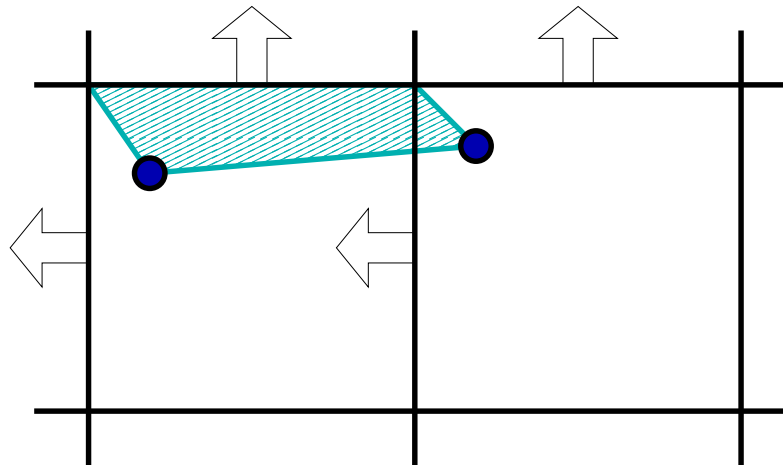
Solution: Cast problem in flux-form

Given $\mathcal{F}^{(SE)}$ find swept areas, $\delta\Omega$, so that:

①

$$\mathcal{F}^{(CSLAM)} = \int_{\delta\Omega} \Delta p(x, y) dA = \mathcal{F}^{(SE)} \quad \forall \delta\Omega.$$

- ② The sum of all the swept areas, $\delta\Omega$, span the domain without cracks or overlaps



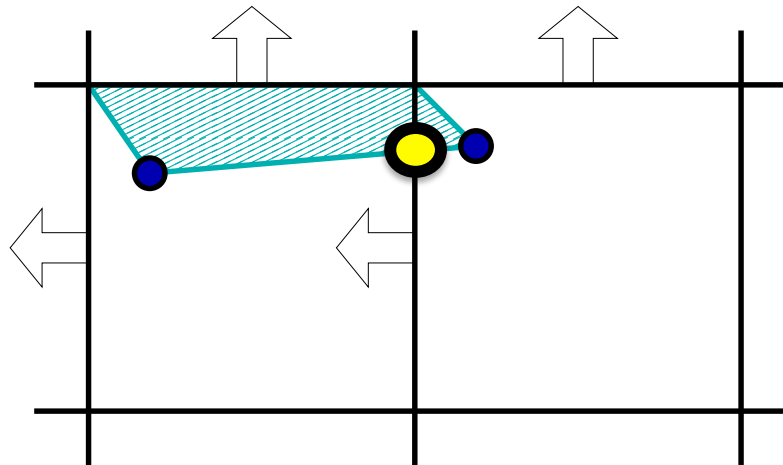
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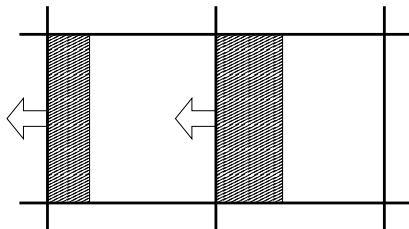
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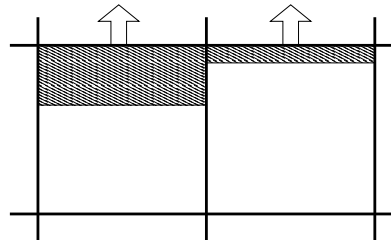
Solution: Cast problem in flux-form

Consistent SE-CSLAM algorithm: step-by-step example

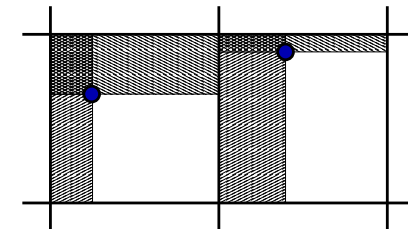
(a) perpendicular x-flux



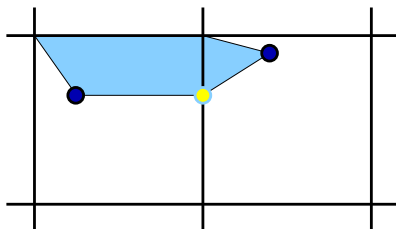
(b) perpendicular y-flux



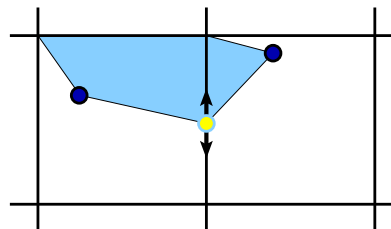
(c) departure points



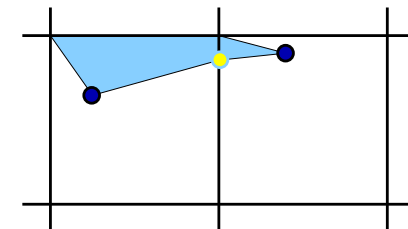
(d) 1st guess swept area



(e) 1st iteration swept area



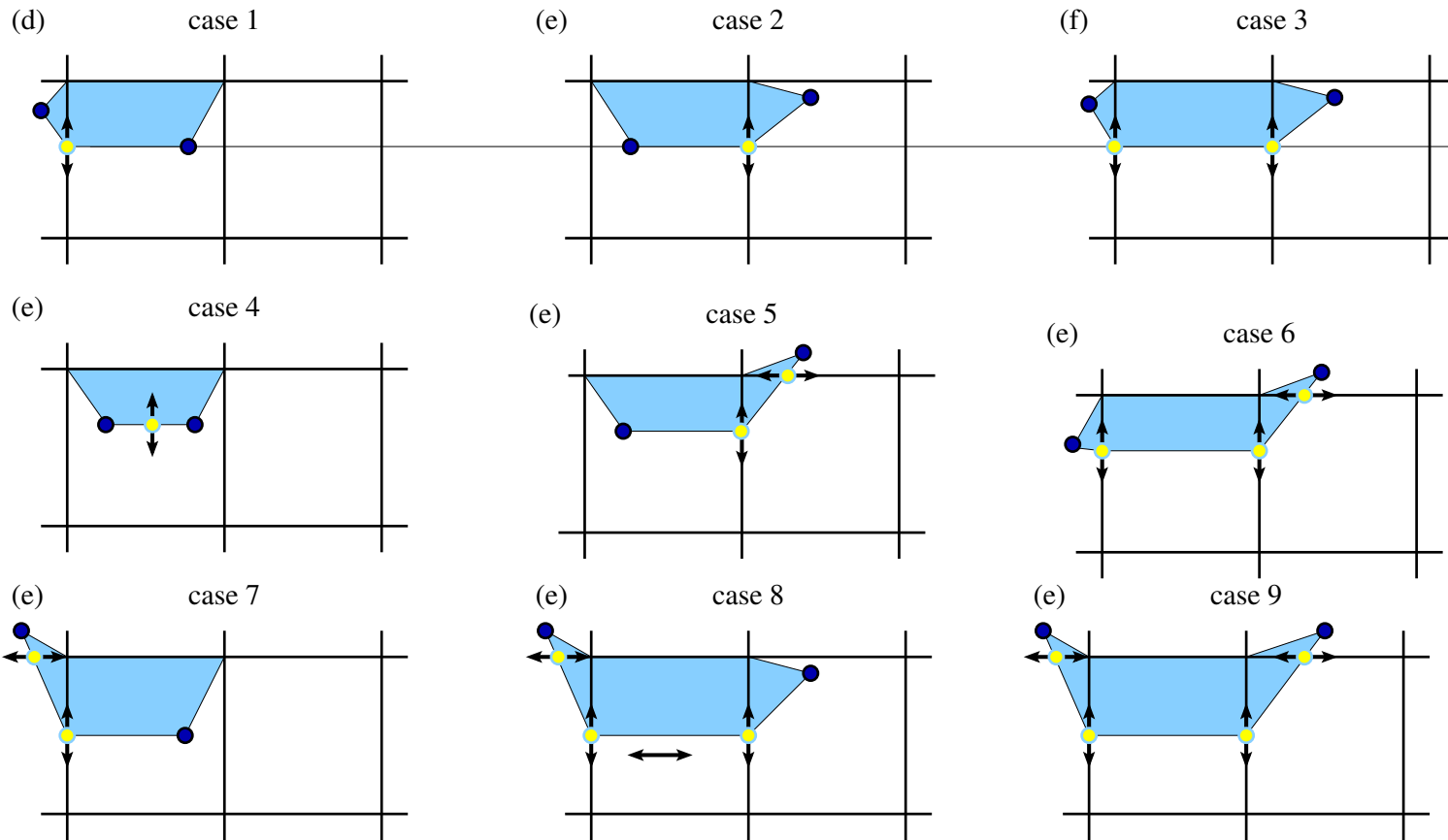
(f) SE consistent flux



Well-posed? As long as flow deformation $\left| \frac{\partial u}{\partial x} \right| \Delta t \lesssim 1$ (Lipschitz criterion)

Solution: Cast problem in flux-form

Consistent SE-CSLAM algorithm: flow cases



4. Consistency

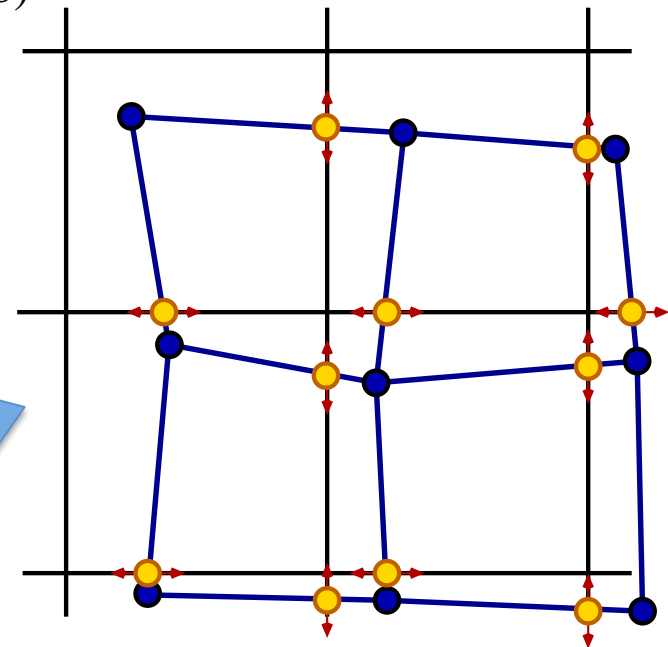
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$$\Delta p_k^{n+1}(\text{CAM-SE}) = \frac{1}{\Delta A} \int_{a_k} \delta p_k^n dA (\text{CSLAM}), \quad (4)$$

Local iteration problem to find equivalent upstream areas:



(b)



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Lauritzen, Taylor, Overfelt, Ullrich and Goldhaber (2016, IN PREP)

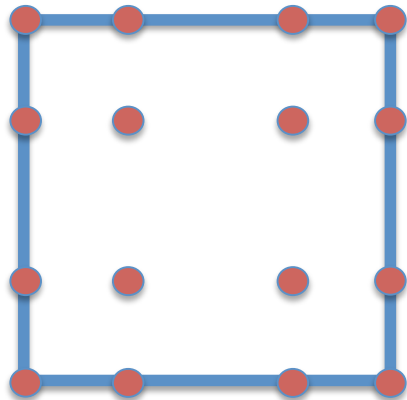


CAM-SE-CSLAM

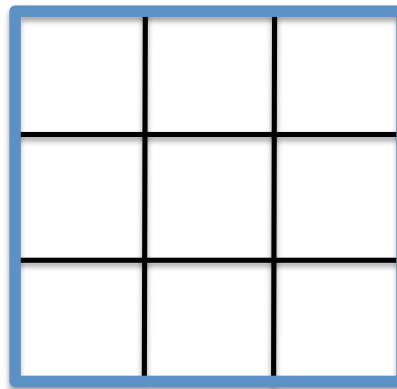
A new model configuration based on CAM-SE:

- **SE:** Spectral-element dynamical core solving for \vec{v} , T , p_s
(Dennis et al., 2012; Evans et al., 2012; Taylor and Fournier, 2010; Taylor et al., 1997)
- **CSLAM:** Semi-Lagrangian finite-volume transport scheme for tracers
(Lauritzen et al., 2010; Erath et al., 2013, 2012; Harris et al., 2010)
- **Phys-grid:** Separating physics and dynamics grids, i.e. ability to compute physics tendencies based on cell-averaged values within each element instead of quadrature points

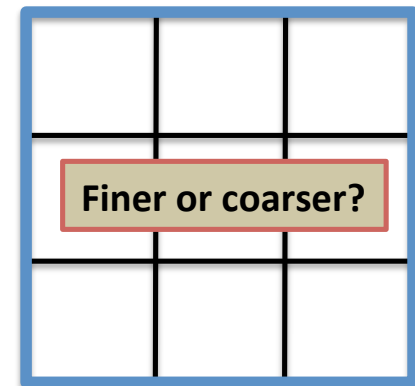
Dynamics grid



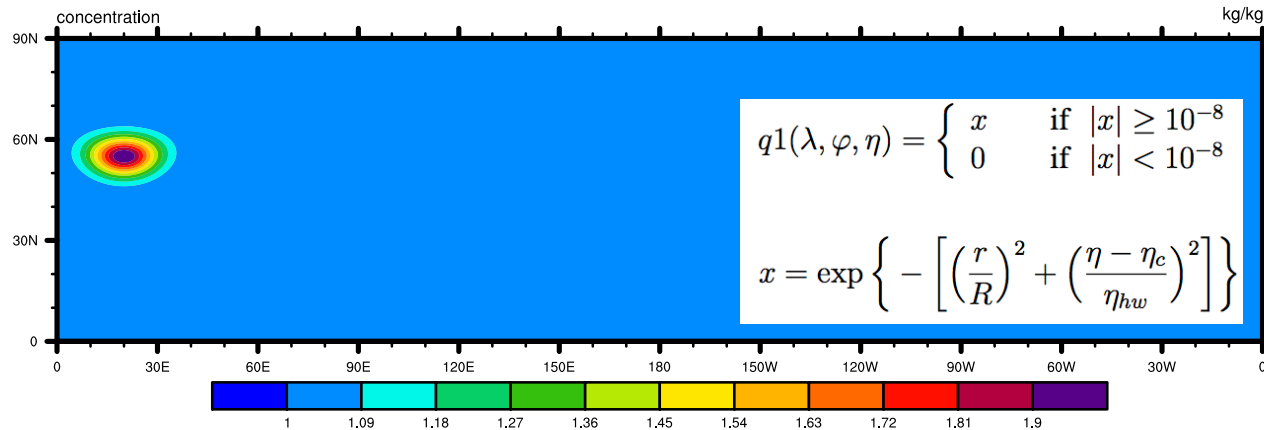
CSLAM grid



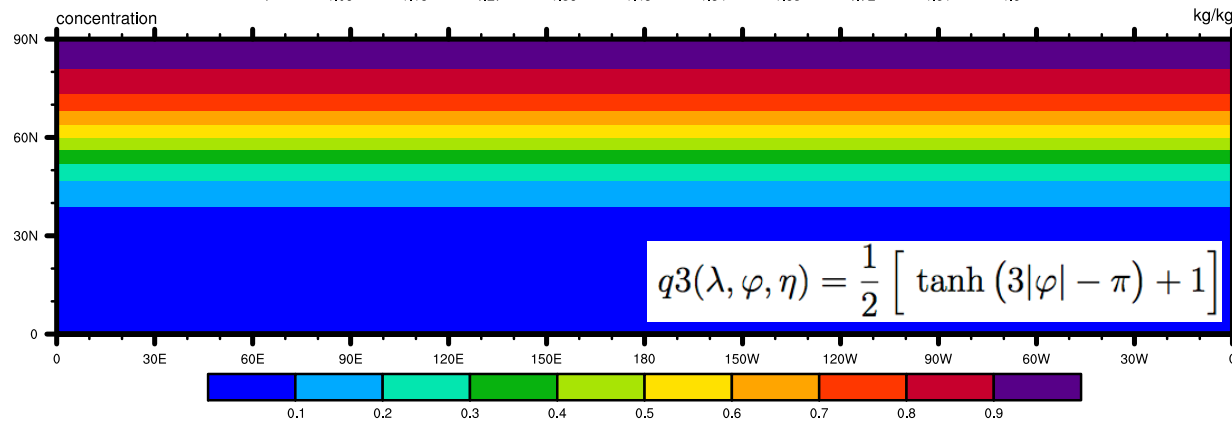
Physics grid



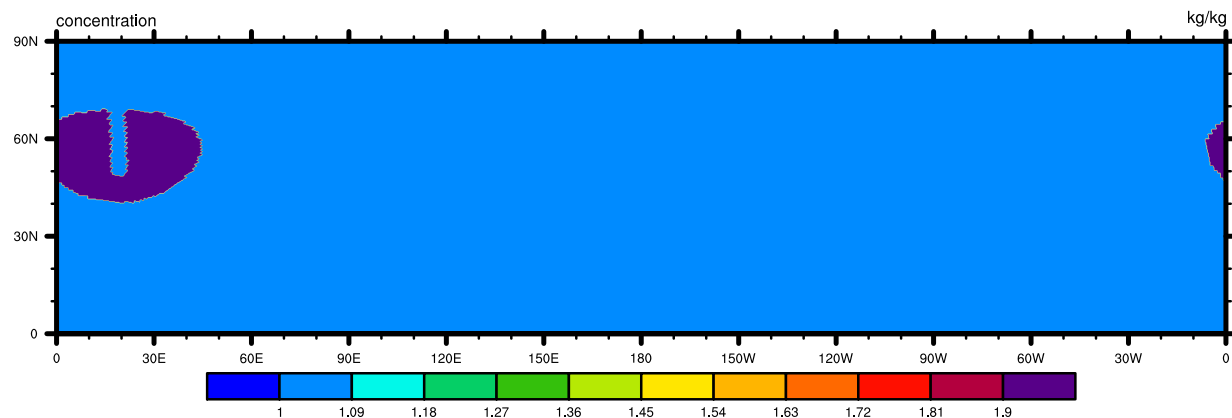
3 tracers: initial conditions



Gaussian
"ball"

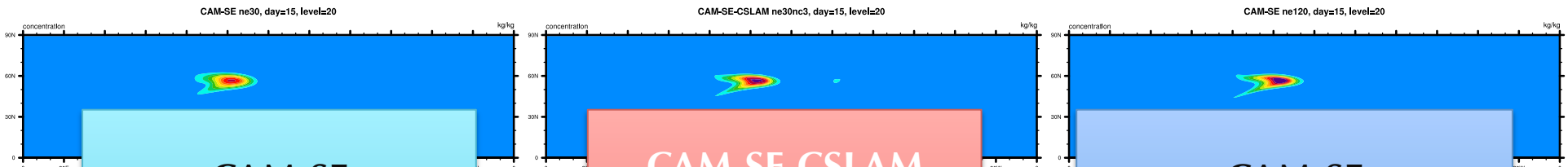
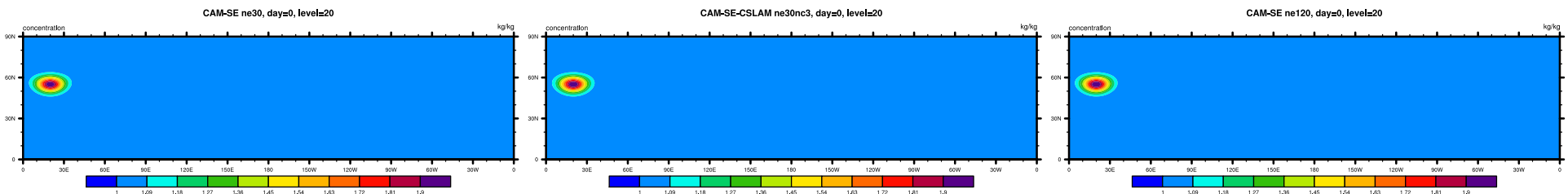


Zonally
symmetric
(smooth)



Slotted
cylinder



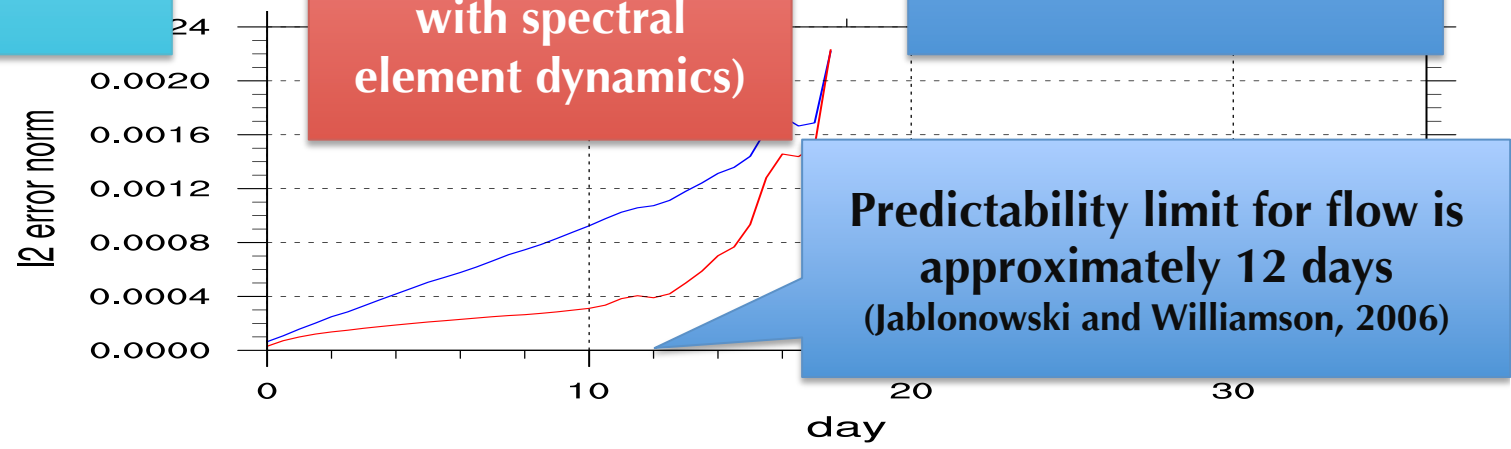


**CAM-SE
1 degree
standard
configuration
(spectral element
advection)**

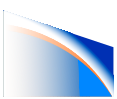
**CAM-SE-CSLAM
1 degree
configuration
(tracer transport
with CSLAM
consistently coupled
with spectral
element dynamics)**

**CAM-SE
0.25 degree
standard configuration

USED AS REFERENCE
SOLUTION ("TRUTH")**



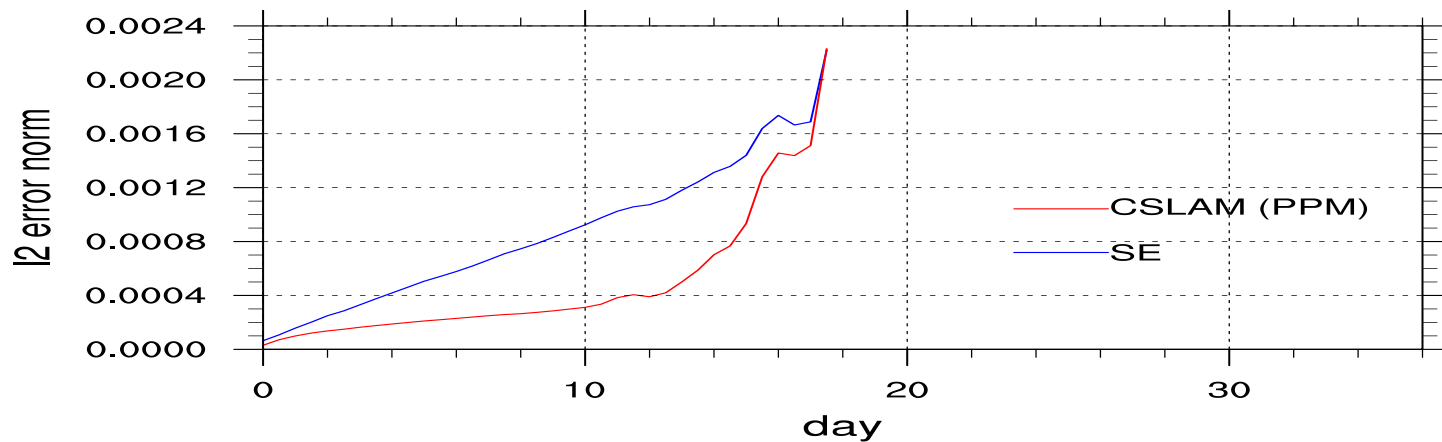
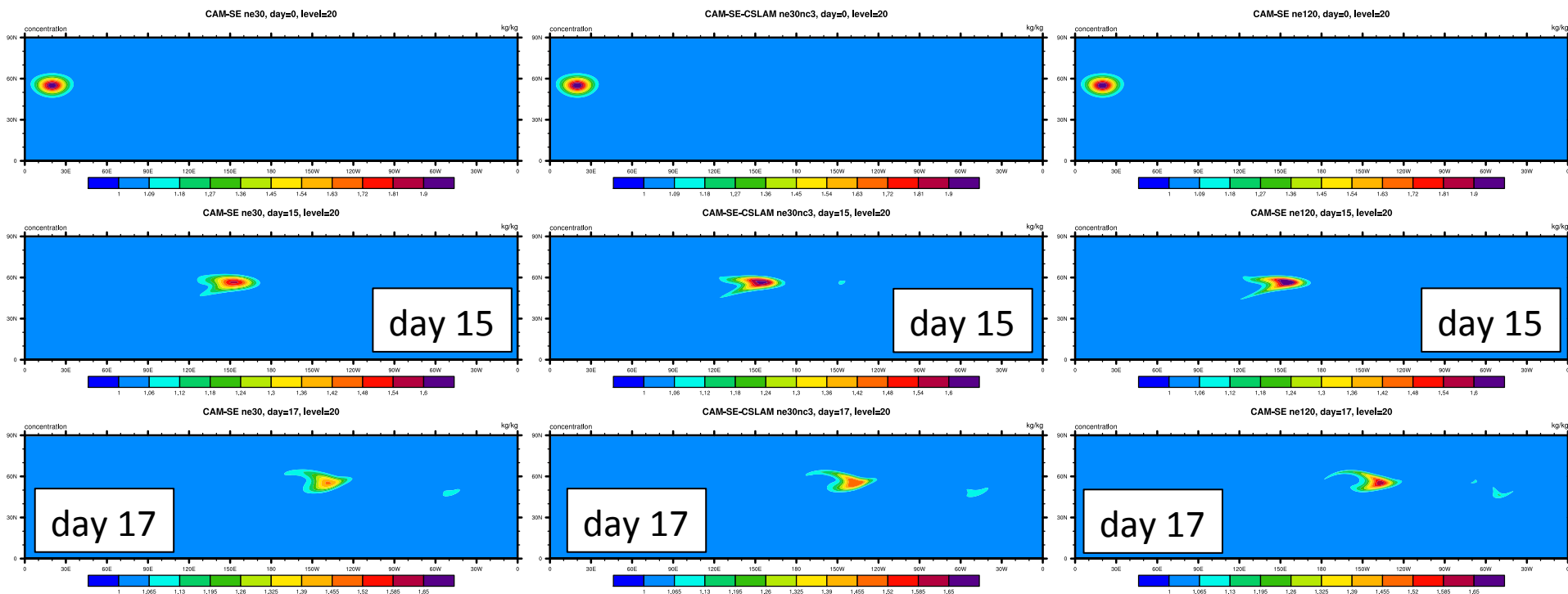
**Predictability limit for flow is
approximately 12 days
(Jablonowski and Williamson, 2006)**



CAM-SE

CAM-SE-CSLAM

CAM-SE reference

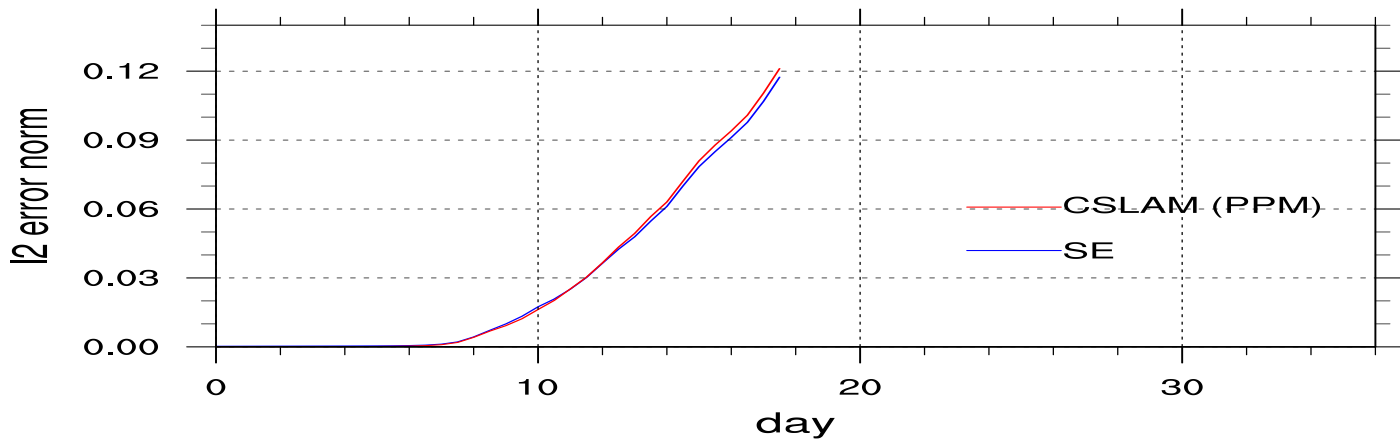
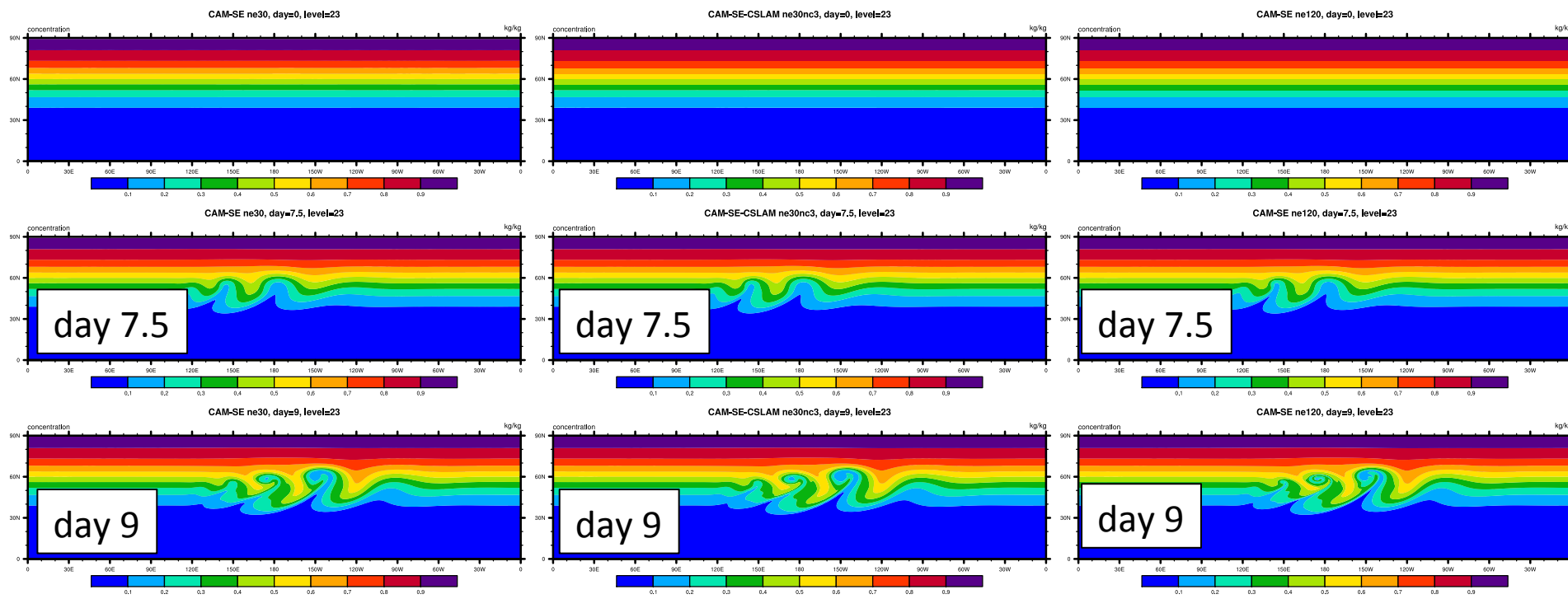


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CAM-SE

CAM-SE-CSLAM

CAM-SE reference

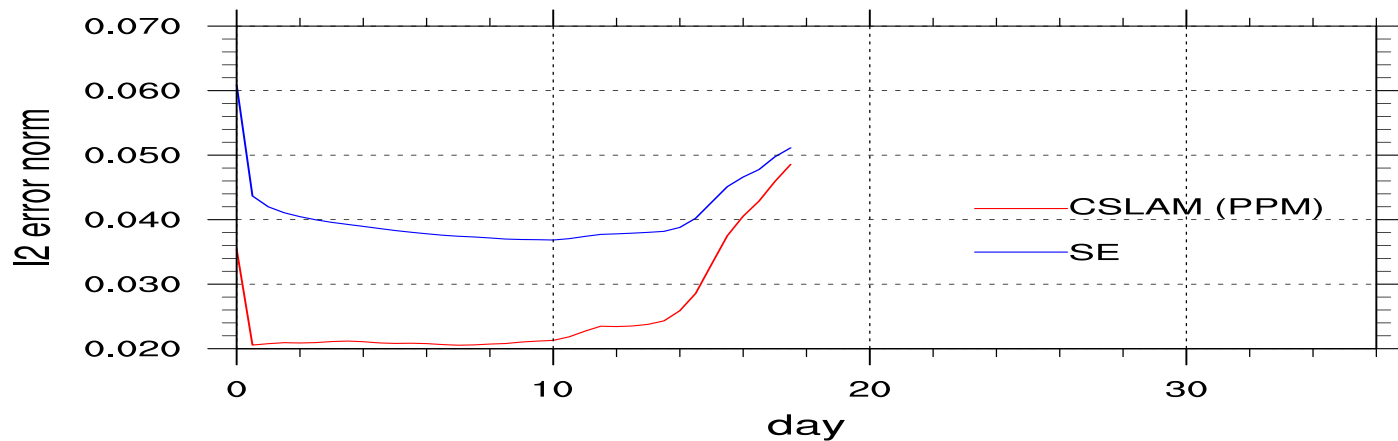
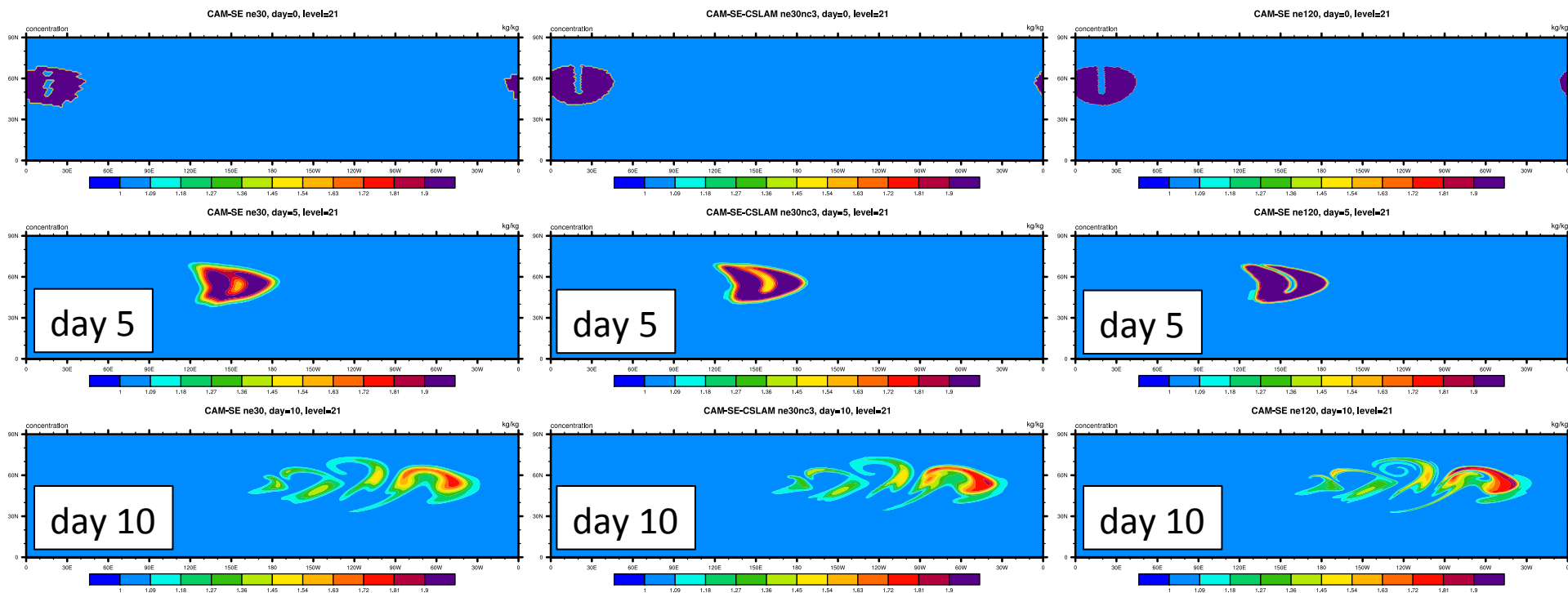


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CAM-SE

CAM-SE-CSLAM

CAM-SE reference

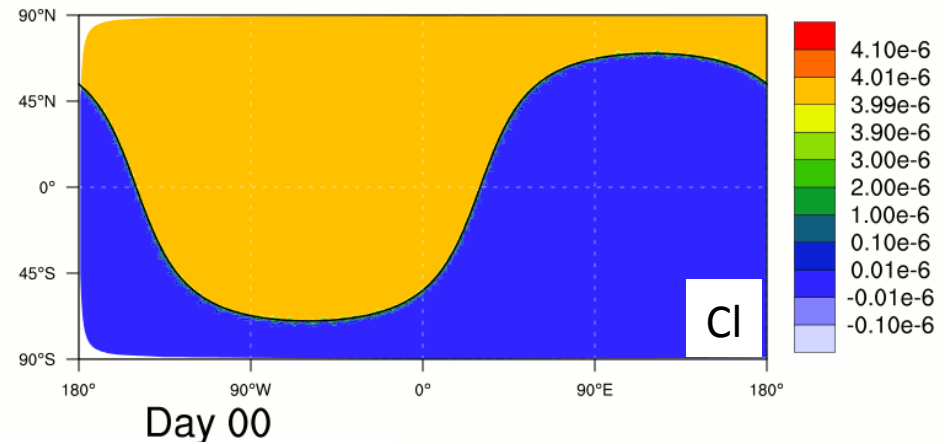
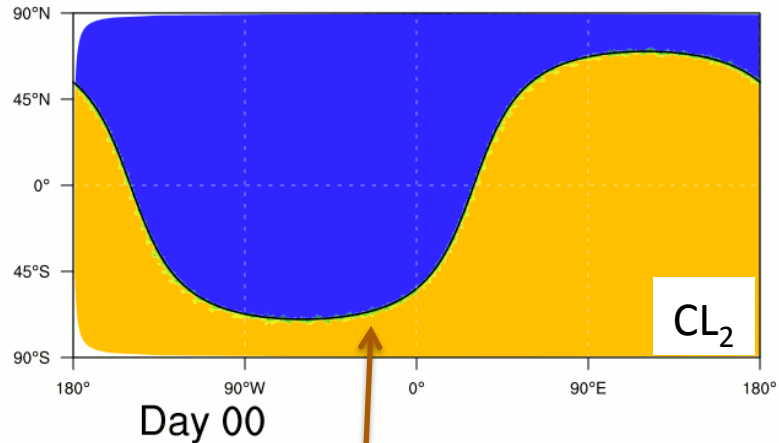


NCAR

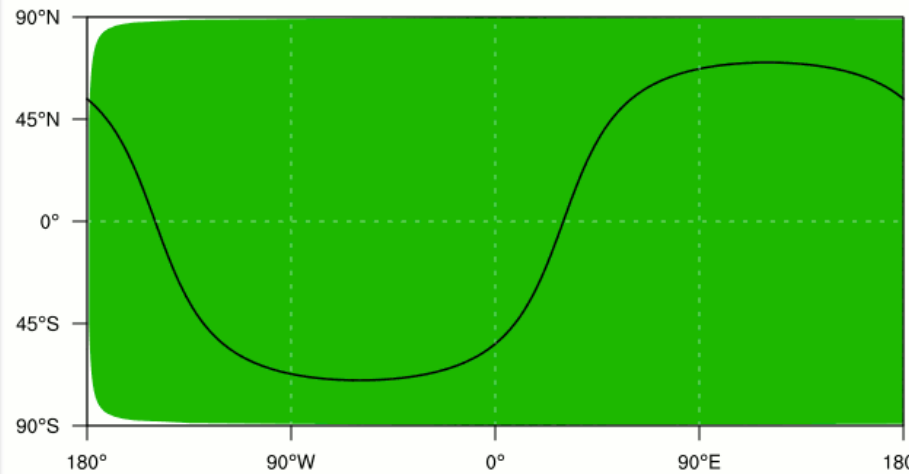
The terminator 'toy'-chemistry test: A simple tool to assess errors in transport schemes

(Lauritzen et al., 2015, GMD)

See: <http://www.cgd.ucar.edu/cms/pel/terminator.html>



$$Cl + 2 * Cl_2 = \text{constant}$$



Non-linear Terminator 'toy' chemistry:

$$Cl_2 \rightarrow Cl + Cl : k_1$$

$$Cl + Cl \rightarrow Cl_2 : k_2$$

Exact solution:
 $Cl + 2 * Cl_2 = \text{constant}$

Wind field:
 Nair and Lauritzen deformational flow

Errors are due to non-conservation of linear correlations usually caused by the limiter/filter and/or physics-dynamics coupling!



'Toy' terminator chemistry code:

In terms of Fortran code the analytical forcing is given by:

```
! dt is size of physics time step  
c1y = c1 + 2.0*c12
```

```
r = k1 / (4.0*k2)  
d = sqrt( r*r + 2.0*r*c1y )  
e = exp( -4.0*k2*d*dt )
```

```
if( abs(d*k2*dt) .gt. 1e-16 )  
  e1 = (1.0-e) / (d*dt)  
else  
  e1 = 4.0*k2  
endif
```

```
f_c1 = -e1 * (c1-d+r) * (c1+d+r) / (1.0 + e + dt*e1*(c1+r))  
f_c12 = -f_c1 / 2.0
```



3D version of terminator test

The terminator test setup can be used in any flow field and the analytical solution for Cl_y is always known!

- Use baroclinic wave setup (a variation of Ullrich et al., 2015)
- Initialize with same mixing ratio distribution in each layer (same as 2D test)
- As a diagnostic we use average column integrated mixing ratios (q) so that diagnostics are independent of vertical coordinate:

$$\langle q \rangle = \frac{\int_{z=0}^{z_{top}} q dz}{\int_{z=0}^{z_{top}} dz}.$$

- Since exact solution is known ($q_{Cl_y} = 4E-6$ kg/kg) we can compute error norms:

$l_2(t)$, $l_\infty(t)$ and relative mass change $\Delta M(t)$ error norms for Cl_y :

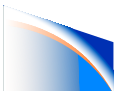
$$l_2(t) = \frac{\sqrt{\int_{z=0}^{z_{top}} (\langle q_{Cl_y} \rangle - 4.0 \times 10^{-6})^2 dz}}{\sqrt{\int_{z=0}^{z_{top}} (4.0 \times 10^{-6})^2 dz}},$$
$$l_\infty(t) = \frac{\max_{\lambda, \theta} |\langle q_{Cl_y} \rangle - 4.0 \times 10^{-6}|}{4.0 \times 10^{-6}},$$
$$\Delta M(t) = \frac{\int_{z=0}^{z_{top}} q_{Cl_y} dz - M_0}{M_0}$$

respectively, where

$$\langle q_{Cl_y} \rangle = \langle q_{Cl_1} + 2q_{Cl_2} \rangle.$$

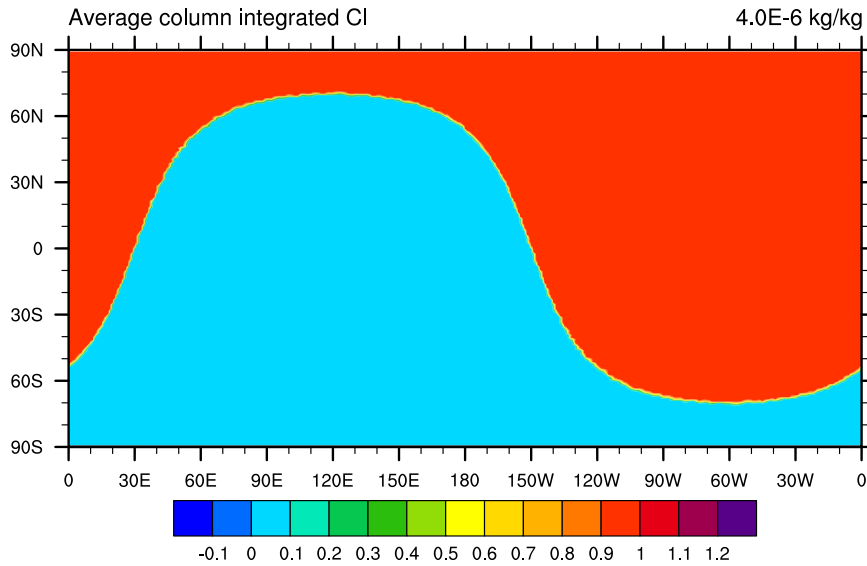
and M_0 is the initial mass of Cl_y

$$M_0 = \int_{z=0}^{z_{top}} 4.0 \times 10^{-6} dz.$$

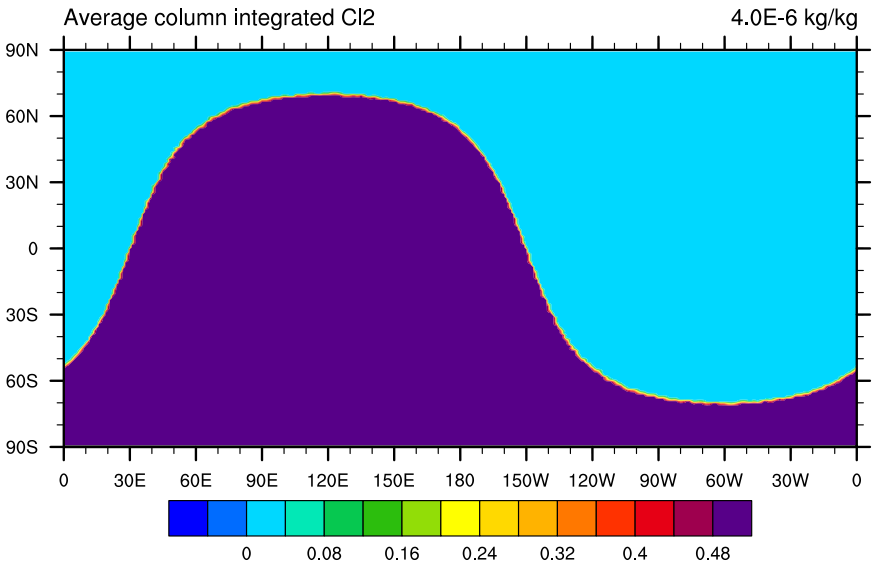


Initial condition

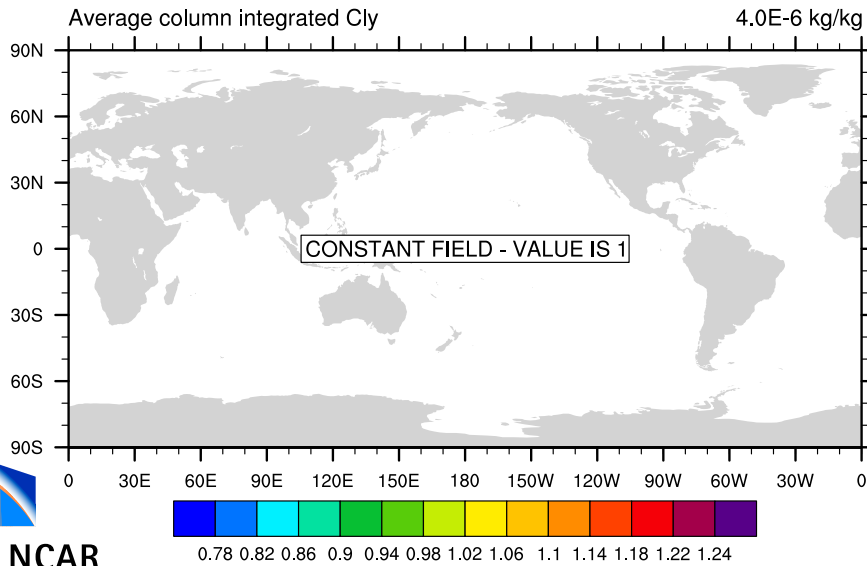
day 0



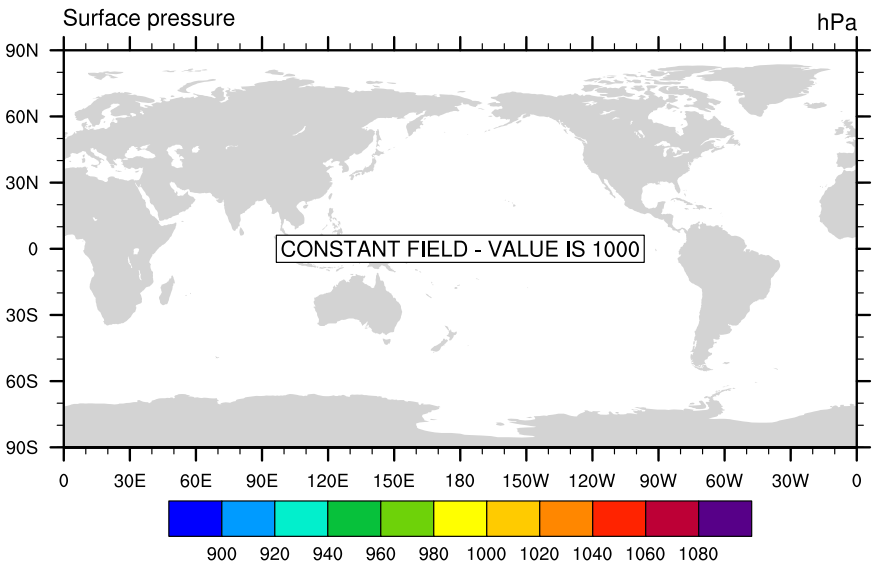
day 0



day 0



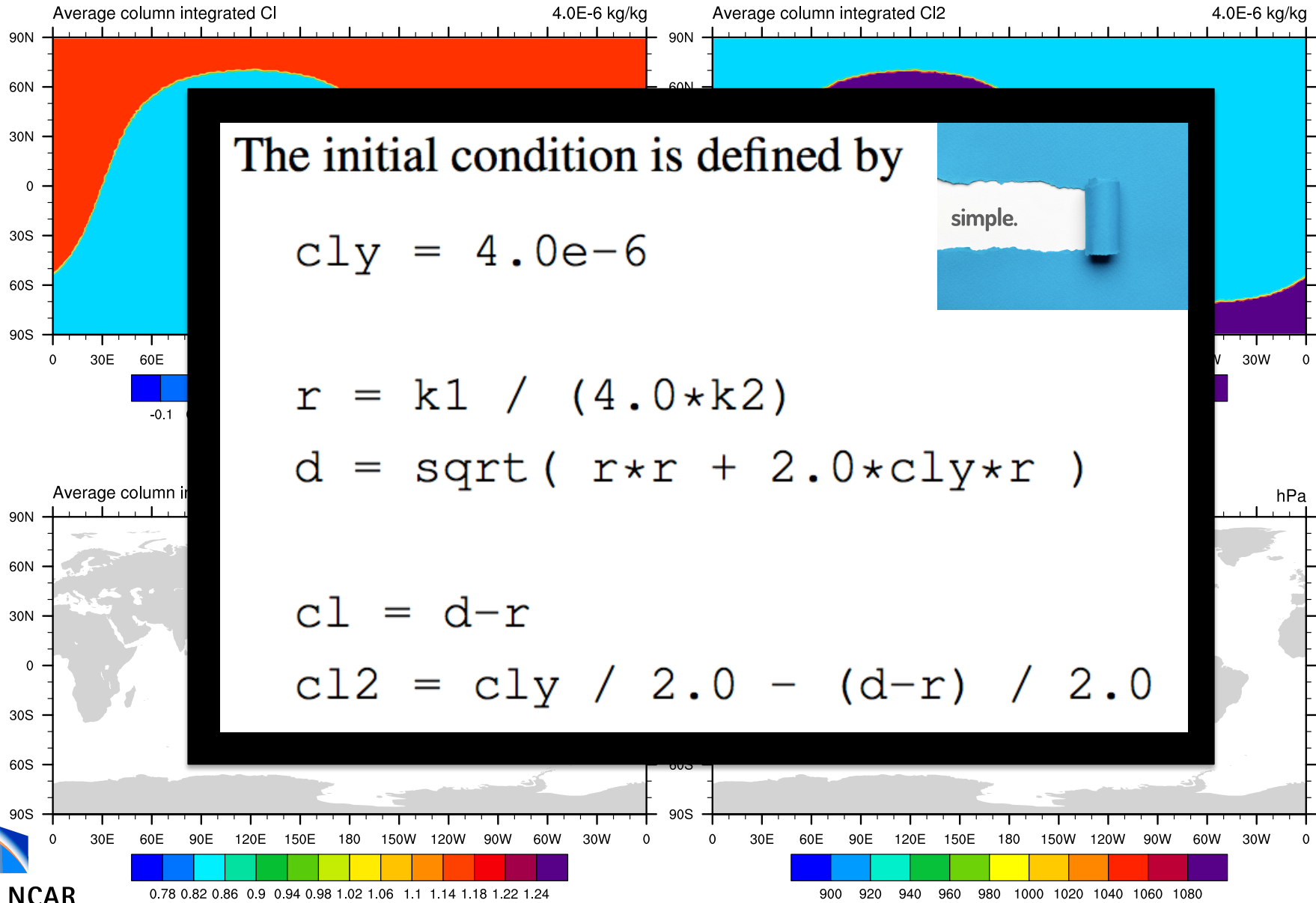
day 0



Initial condition

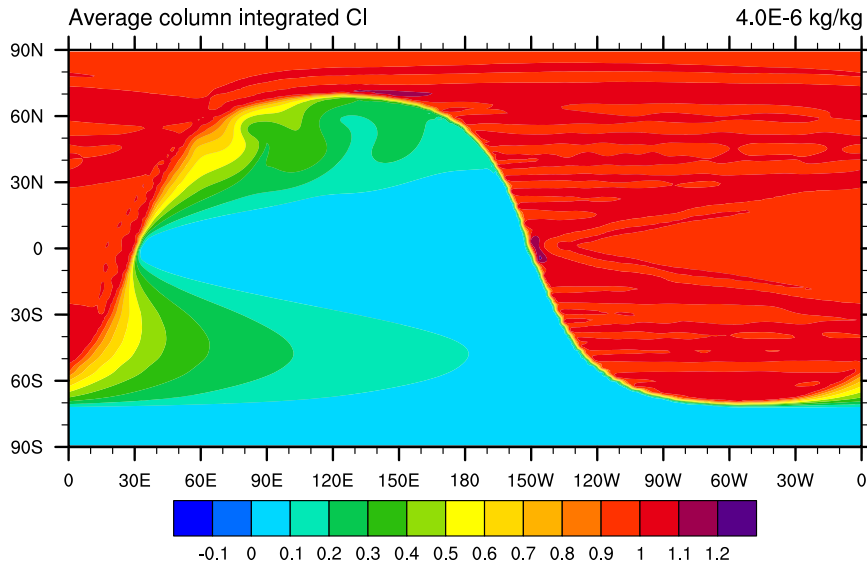
day 0

day 0

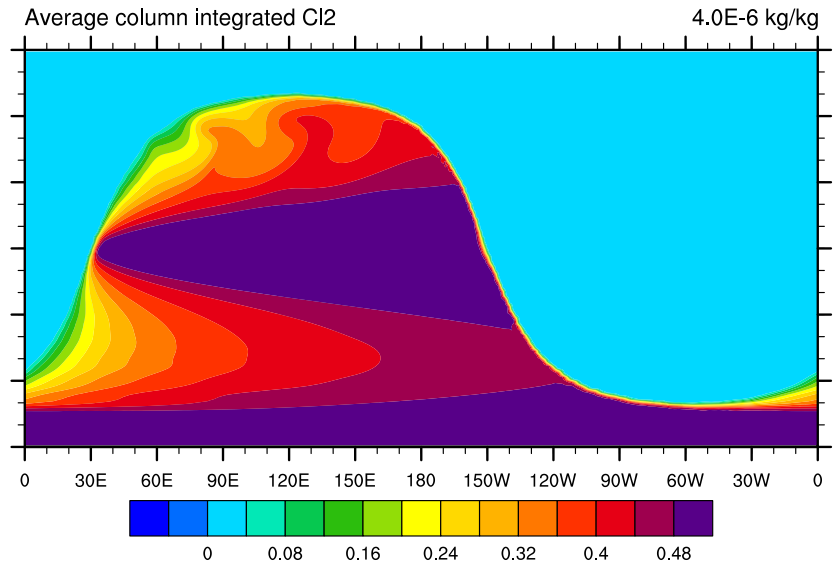


CAM-SE

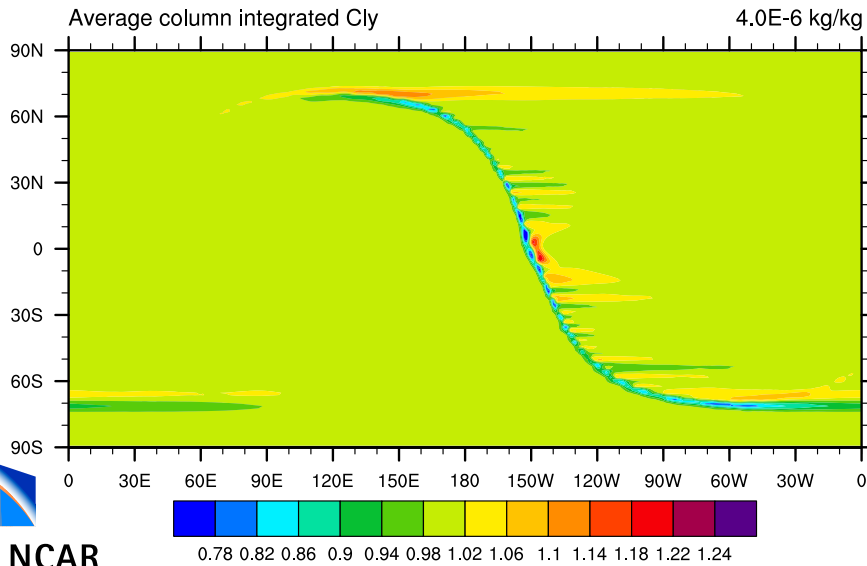
day 9



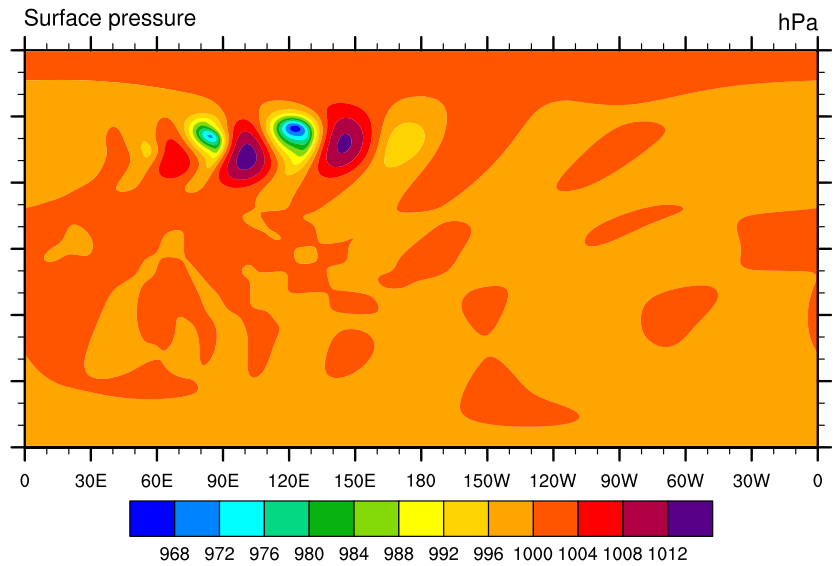
day 9



day 9



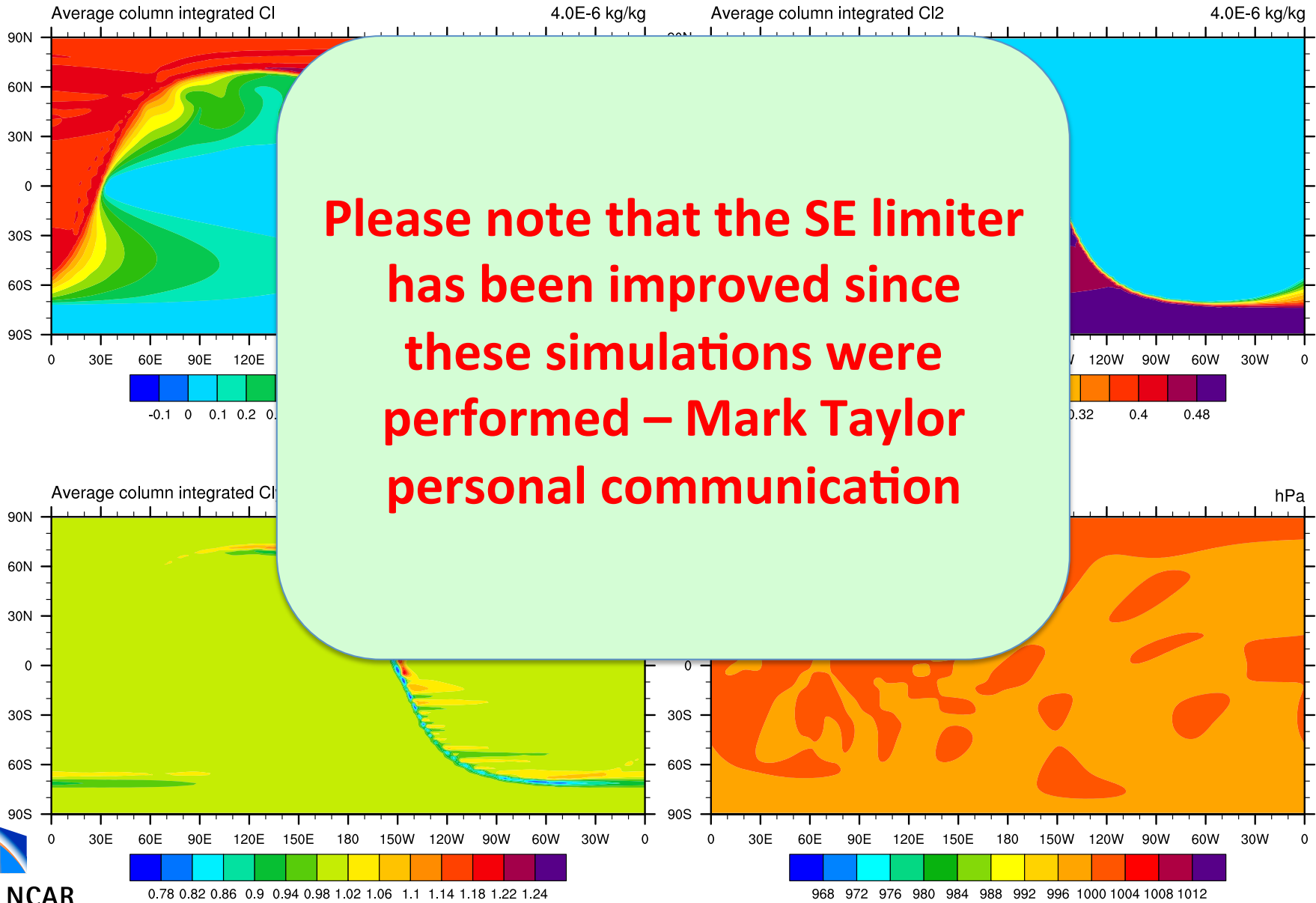
day 9



CAM-SE

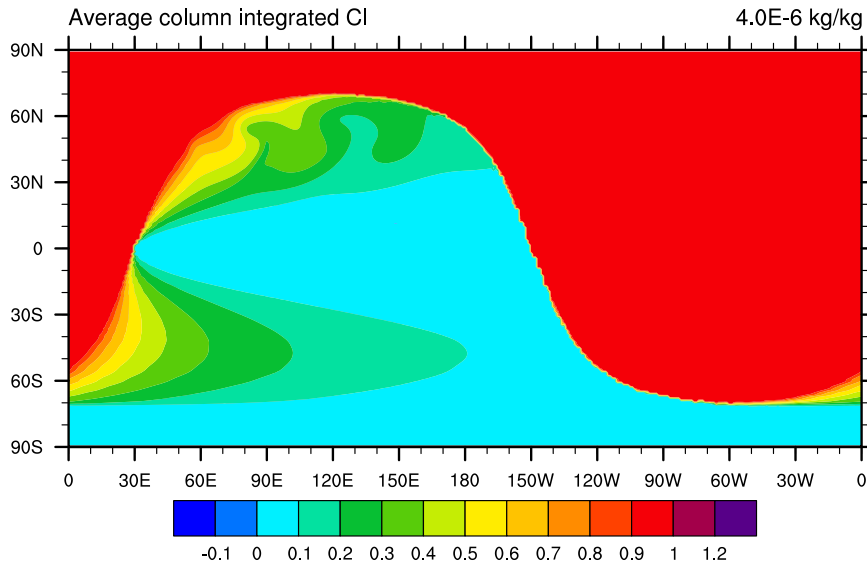
day 9

day 9

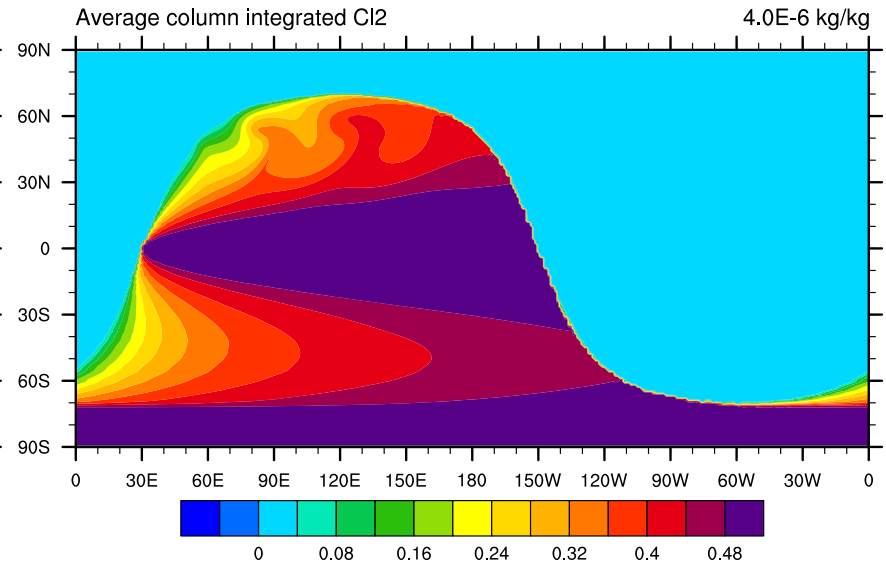


CAM-SE-CSLAM

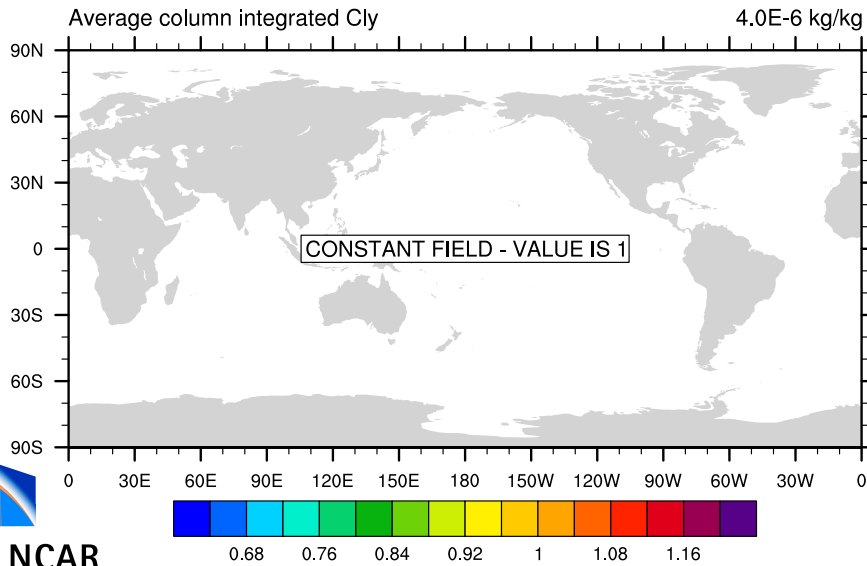
day 9



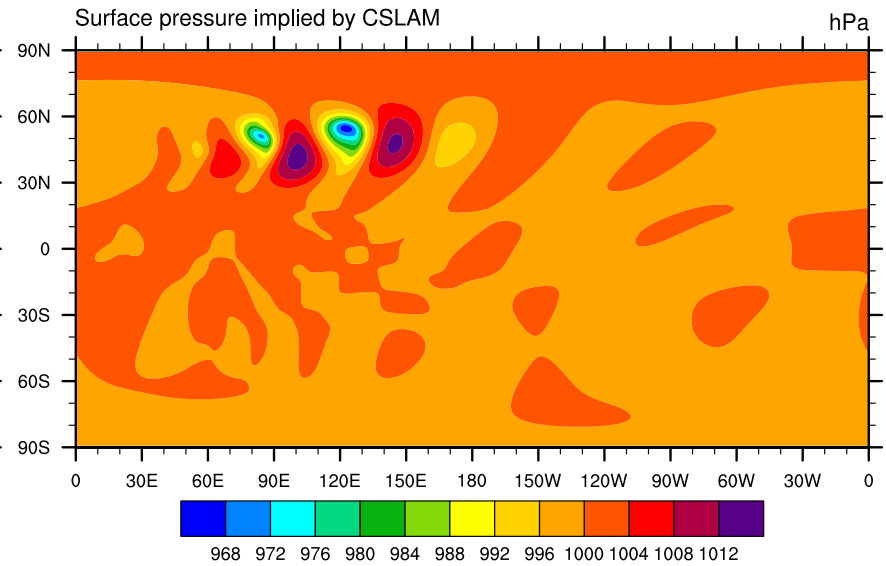
day 9



day 9

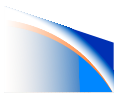
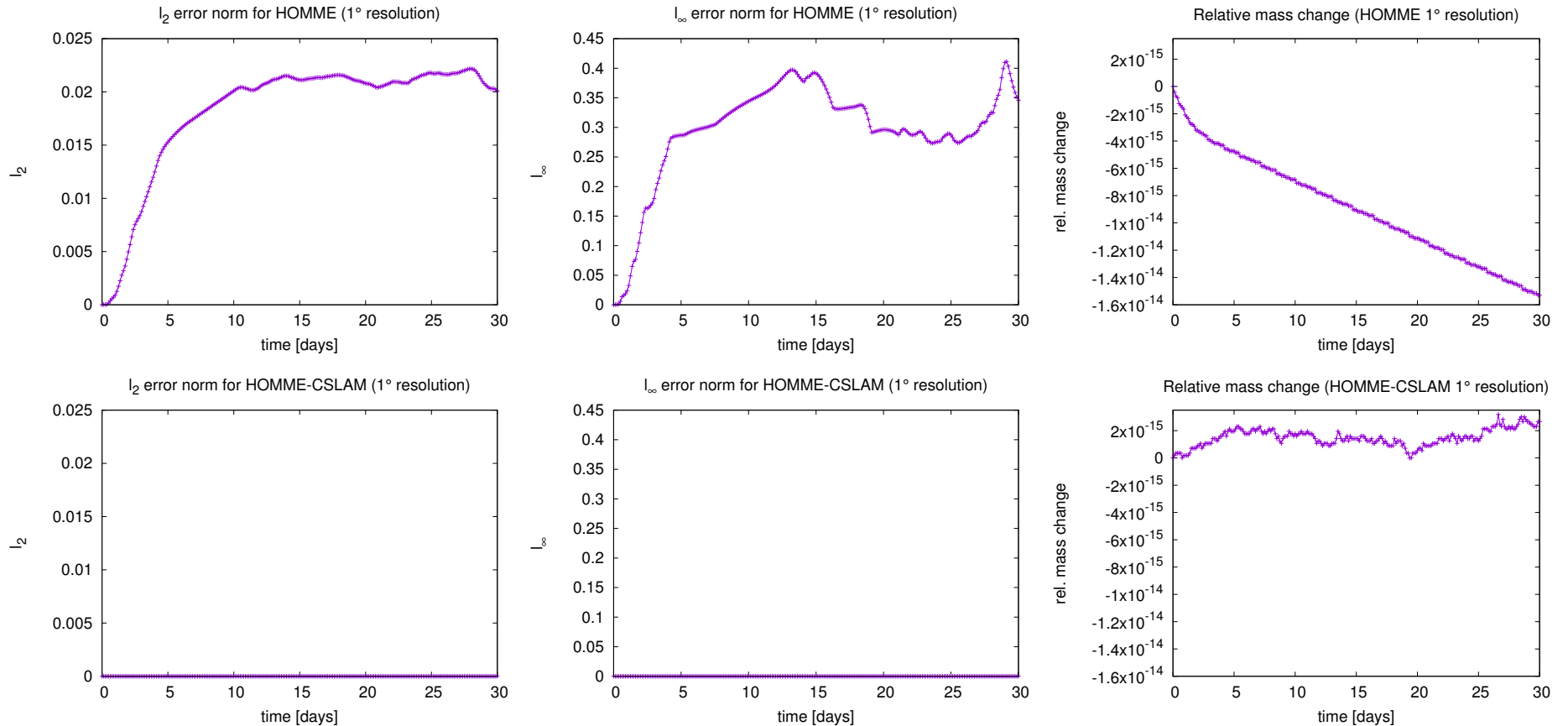


day 9



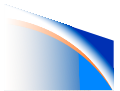
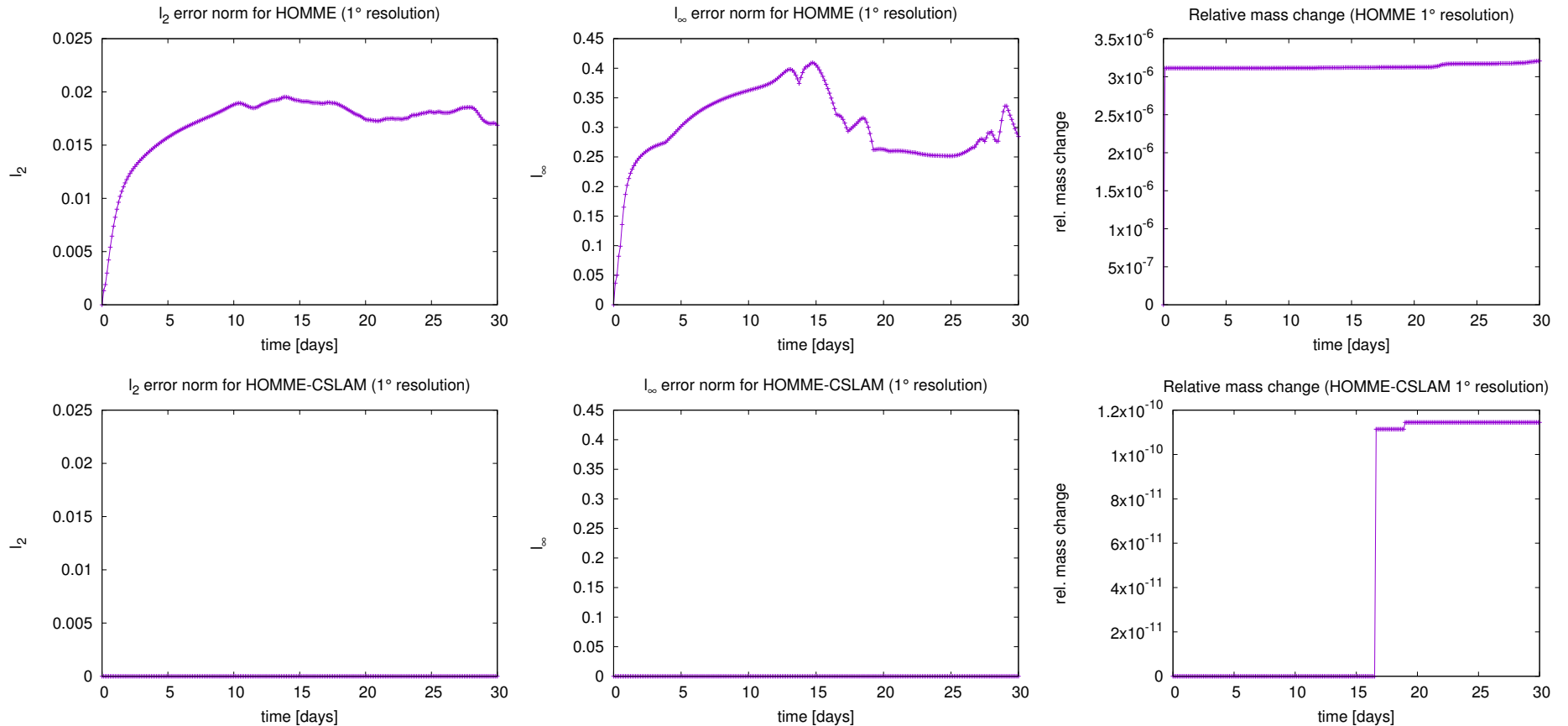
CAM-SE-CSLAM

Diagnostics for terminator test: chemistry time-step = 900s



CAM-SE and CAM-SE-CSLAM

Diagnostics for terminator test: chemistry time-step = 1800s



CAM-SE and CAM-SE-CSLAM

Mass-conservation of Cl_y violated by physics-dynamics coupling:

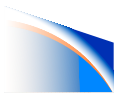
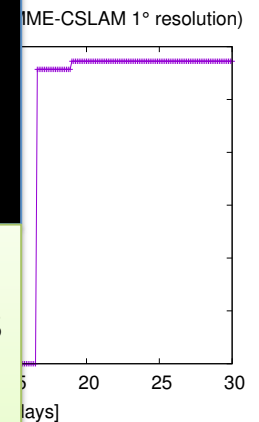
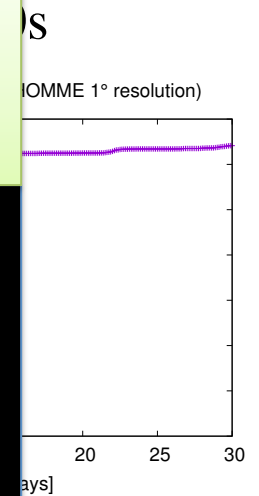
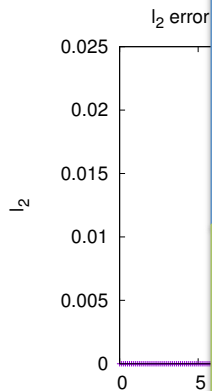
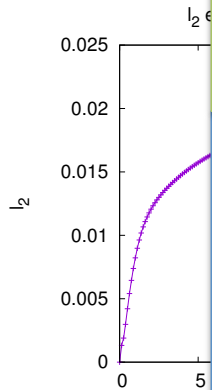
```

do i=C1,C12
  ! dt is size of physics time step
  F=dt*F_i
  if (q_i+F<0) then
    if (q_i<0) then
      !don't make negate q more negative
      F=0
    else
      ! make forcing as close as possible to f_q without making q negative
      F=-q_i
    end if
  end if
  q_i=q_i+F
end do

```

Example: if forcing for q_{Cl} is modified by if-statement then $F_{Cl} \neq -2F_{Cl2}$ and preservation of linear correlations by physics-dynamics coupling is violated and thereby mass-conservation of Cl_y is violated!

Occurs at a point 2 times for CAM-SE-CSLAM and frequently (in time and space) for CAM-SE.



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