Dynamical core development



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Requirements

- 1. Scalable O(100k+) cores
- 2. **Conservation** of energy and tracer masses (locally)
- 3. **Consistent** and **shape-preserving** tracer transport
- 4. **Reasonable spectra** of kinetic energy, temperature and tracers
- 5. **Economical**, i.e. no more expensive than current methods of choice for comparable quality solution
- 6. Static mesh-refinement capability to allow regional climate studies in contrast to or complementary to nested modeling (at this stage probably not a requirement but we think the modeling community is moving in that direction!)
- 7. It is highly desirable that **developers collaborate** with staff and remain **responsive** when problems appear
- Note: Since frictional heating occurs on scales well below the truncation limit, 2) and 4) imply a fixer will most certainly be needed.



Some dynamical core efforts

(in random order)

- MIT General Circulation Model (MITgcm)
- High-Order Modeling Environment (HOMME), NCAR & DOE.
- GFDL's Climate Model (CM3)
- NASA's cubed-sphere version of Goddard Earth Observing System (GEOS)
- EULerian and LAGrangian framework (EULAG) on a "stretched lat-lon grid" with static mesh-refinement capability coupled to CAM3 physics (CAM-EULAG), lowa State University.

- Colorado State University General Circulation Model (CSUgcm)
- Model for Prediction Across Scales (MPAS), NCAR & DOE
- Flow-following finite-volume Icosahedral Model (FIM), NOAA
- Ocean-Land-Atmosphere-Model (OLAM), Duke University

Icosahedral

- Non-hydrostatic ICosahedral Atmospheric Model (NICAM), JAMSTEC, Japan
- ICOsahedral Nonhydrostatic general circulation model, (ICON-GCM), MPI-M, Germany

Yin-Yang



Lat-lon

NCAR



Cubed-sphere

2008 NCAR Summer Colloquium on Dynamical Cores

Adiabatic rotated steady-state test case (Lauritzen et al., 2010, Journal of Advances in Modeling Earth Systems)

Day 9, approximately 2° horizontal resolution at equator



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Remapping (conservative interpolation)

Note: To couple dynamical cores defined on non-traditional grids to other component models (land, ocean, ...) might need more robust (and perhaps more accurate) remapping software and support for regional grids.

Could become a show-stopper if new software is not developed or if existing software is not "upgraded"!



Some suggestions for idealized testing of dynamical cores

Passive advection: 2D and 3D translational, divergent and deformational flows on the sphere

- tests advective operator in settings where the analytic solution is usually known (Williamson et al., 1992, Nair and Machenhauer 2002, Nair and Jablonowski 2008, Nair and Lauritzen 2010, etc.)

Adiabatic : Baroclinic wave (non-rotated and rotated)

- analytic solution not known but reference solutions and the uncertainty of the reference solutions "known" => test can be used to determine at what resolution the dynamical core has converged (Jablonowski and Williamson, 2006)
- rotated version: Is the solution method isotropic? (Lauritzen et al. 2010)

Idealized physics: Held-Suarez

- simplified physics (Held and Suarez, 1994)

Aqua-planet using the same physics package

- Simplified surface but full physics (Neale and Hoskins, 2001)

• More global idealized tests are (probably) needed! Suggestions?

• We find fora where models are tested against each other using the same test suite useful (e.g., 2008 NCAR ASP Colloquium)

A dynamical core intercomparison workshop is planned in 2012 (Jablonowski, Lauritzen, Taylor, Nair)

Physics-dynamics interface/coupling

- Total energy is not treated consistently in CAM
- Should we add the infrastructure to CAM so that the physics can be run on a different grid (both in the vertical and horizontal)?
- Other?

Coupling the dynamical core to physics and the impact of how that is done is still an underexplored, yet important, area of research







- Should we support multiple dynamical cores?
- Should we use the same dynamical core at all resolutions (coarse paleoclimate to high regional climate resolutions)?
 (remember that user base extends from linux-cluster users to massively parallel system users)
- Should we keep supporting "old" dynamical cores (CAM-EUL, CAM-SL, CAM-FV)?



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Functionality?

- Should we require the dynamical core to be non-hydrostatic in this development cycle?
- Should we require functionality to run in a doubly-periodic-plane-mode for idealized testing of parameterizations?

