Design of Atmosphere Models Based on the Nonhydrostatic Unified System of Equations in the Height and Sigma Vertical Coordinates

Ross Heikes, Celal Konor and David Randall, Colorado State University

- We present a brief description of the Unified Z-grid Icosahedral Model (UZIM). Results from various standard test cases are also presented.
- The unified system is a nonhydrostatic system applicable to the global cloud resolving models. It unifies the quasi-hydrostatic and anelastic systems.
- The model uses an icosahedral grid with Z-grid staggering.
- The height vertical coordinate version of the model (UZIM-height) is nearing completion. This version uses a Lorenz vertical grid.
- The quasi-hydrostatic hybrid sigma-pressure vertical coordinate version of the model (UZIM-sigma) has been completed. Nonhydrostatic version is under development.

Results from several test runs are presented in the poster



Warm Bubble Experiment (UZIM-height)

G6 (grid distance=115 m) 96L (vertical grid distance=125 m) a=6.37 km, ztop=12km



Quasi-hydrostatic and Nonhydrostatic Gravity Wave Propagation (UZIM-height)

G6 (grid distance=1000 m) 10L (vertical grid distance=1000 m) a=51 km, ztop=10km





See DCMIP website (https://www.earthsystemcog.org/projects/dcmip-2012/) for comparison to other models

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Overview:

We present a global nonhydrostatic dynamical core based on the unified system of equations (Arakawa and Konor, MWR, 2009; and Konor, MWR, 2014). The dynamical core uses an icosahedral horizontal grid and Z-grid staggering (Randall, MWR, 1994). We call the model as the Unified Z-grid Icosahedral Model (UZIM). There are two versions of the UZIM: 1) the height vertical coordinate version which uses a Lorenz grid (UZIM-height), and 2) the hybrid sigma-pressure coordinate version which uses a Charney-Phillips grid (UZIM-sigma). The quasi-hydrostatic version of the UZIM-sigma has been completed. The nonhydrostatic version is under development.





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Vertical L-grid of UZIM-height

Vertical CP-grid of UZIM-sigma

<i>w</i> =0	$ \theta w \dot{\sigma}=0$ $$
θ π _{qs} δπ	ζ D z π _{qs} δπ
W	$\theta w \sigma$
$\theta \ \pi_{qs} \ \delta \pi$	$\zeta D z \pi_{qs} \delta \pi_{\bullet\bullet\bullet\bullet}$
W	$\theta w \sigma$
$\theta \pi_{qs} \delta \pi$	$\zeta D Z \pi_{qs} \delta \pi$ - θ w σ=0
w=0	